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Uncertainty and
Irreversibility: too
fast or too slow?**

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We wish to thank Guido Candela for helpful comments. We are also grateful for comments and suggestions to participants at the 12th International BIOECON conference; the 51st SIE conference; the 18th Annual EAERE Conference; the 8th workshop of the International Society of Dynamic Games; and to seminar participants at FEEM & IEFE - Bocconi University, University of Stirling and CERE - Umeå University. The usual disclaimer applies.

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November 9, 2011

Abstract

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1 Introduction

As human population grows, the human-Nature conflict has become more severe and natural habitats are more exposed to conversion. On the one hand, clearing land to develop it may lead to the irreversible reduction or loss of valuable environmental services (hereafter, ES) such as biodiversity conservation, carbon sequestration, watershed control and provision of scenic beauty for recreational activities and ecotourism. On the other hand, conserving land in its pristine state has an opportunity cost in terms of foregone profits from economic activities (e.g. agriculture, commercial forestry) which can be undertaken once land has been cleared.¹

At a society level, the problem is then how to allocate the available land given two possible competing and mutually exclusive uses, namely conservation and development. The choice should be taken by optimally balancing social benefit and cost of conservation. However, despite its theoretical appeal, the idea of a social planner who, once defined a socially optimal land conversion rule, can implement it by simply commanding the constitution of protected areas, is far from reality. In fact, since the majority of remaining ecosystems are on land privately owned, the economic and political cost of such intervention would make the adoption of command mechanisms by Governments unlikely (Langpap and Wu, 2004; Sierra and Russman, 2006). In addition, as pointed out by Folke et al. (1996, p. 1019), "*keeping humans out of nature through a protected-area strategy may buy time, but it does not address the factors in society driving the loss of biodiversity*". In other words, protecting natural ecosystems through natural reserves and other protected areas may be a significant step in the short-run to deal with severe and immediate threats but it still does not create the structure of incentives able to mitigate the conflict human-Nature in the long-run.

At least initially, Governments favoured an indirect approach in conservation policies. The main idea behind this approach was to divert, through programs such as integrated conservation and development projects, community-based natural resource management or other environment-friendly commercial ventures, the allocation of labour and capital from ecosystem damaging activities toward ecosystem conserving activities (Wells et al., 1992; Ferraro and Simpson, 2002). However, despite the initial enthusiasm, effectiveness and cost-efficiency concerns have led to abandonment of this approach in favour of compensations to be paid directly to the landholders providing conservation services (see e.g. Ferraro, 2001; Ferraro and Kiss, 2002; Ferraro and Simpson, 2005). A direct approach, mainly represented by schemes like Payments for Environmental Services (hereafter, PES) has become increasingly common in both developed and developing countries. Under a PES program, a provider delivers to a buyer a well-defined ES (or corresponding land use) in exchange for an agreed payment.² Unfortunately, also the efficacy of PES programs has been questioned since their performance has not always met the established conservation targets.³ In particular, lack of additionality in the conservation efforts induced by the programs has often been suspected, i.e. landholders have been paid for conserving the same extent of land they would have conserved without the program.⁴ Considering the limited amount of money for conservation initiatives and the perverse effect that wasting it may have on future funding, further research is needed to increase our understanding of the economic agent's conversion decision.

The literature investigating optimal conservation decisions under irreversibility and uncertainty over the net benefits attached to conservation represents a significant branch of environmental and resource economics (see among others Bulte et al., 2002, Kassar and Lassere, 2004; Leroux et al., 2009). A unifying aspect in this literature is the stress on the effect that irreversibility and uncertainty have on decision making. In fact, since irreversible conversion under uncertainty over future prospects may be later regretted, this decision may be postponed to benefit from option value attached to the maintained flexibility (Dixit and Pindyck, 1994). Pioneer papers such as Arrow and Fisher (1974) and Henry (1974) have been followed by several

¹ See Barbier and Burgess (2001) for a theme issue on the economics of tropical deforestation and land use.

² In this respect we follow Wunder (2005, p. 3) where a PES is defined as "(i) a voluntary transaction where (ii) a well-defined ES (or a land-use likely to secure that service) (iii) is being "bought" by a (minimum one) ES buyer (iv) from a (minimum one) ES provider (v) if and only if the ES provider secures ES provision (conditionality)".

³ As reported by Ferraro (2001), this may be due to several reasons such as lack of funding, failures in institutional design, poor definition and weak enforcement of property rights and strategic behaviour by potential ES providers. See Ferraro (2008) on information failures and Smith and Shogren (2002) on specific contract design issues.

⁴ We refer in particular to government-financed programs. On the performance of user vs. government-financed interventions see Pagiola (2008) on PSA program in Costa Rica and Wunder et al. (2008) for a comparative analysis of PES programs in developed and developing countries. See Ferraro and Pattanayak (2006) for a call on empirical monitoring of conservation programs and Pattanayak et al. (2010) for a review of available studies.

other papers dealing with new and challenging questions requiring more and more complex model set-up.⁵ Two contributions close to ours are Bulte et al. (2002) and Leroux et al. (2009). In the first paper, the authors determine the socially optimal forest stock to be held by trading off profit from agriculture and the value of ES attached to forest conservation. Their analysis highlights the value of the option to postpone land clearing under irreversibility of environmental impact and uncertainty about conservation benefits. A similar problem is solved in Leroux et al. (2009) where, unlike the previous paper, the authors allow for ecological feedback and consider its impact both on the expected trend and volatility of the value of ES. Both papers, however, by solving the allocative problem from a central planner perspective, miss the complexity of challenges characterizing conservation policies and the role that competition on markets for agricultural products may have on conversion decisions.

In this paper, we aim to investigate these issues by modelling conversion decisions in a decentralized economy populated by a multitude of homogenous landholders where the Government has introduced a payment scheme for conservation. Each landholder manages a portion of total available land and may conserve or develop it by affording a conversion cost. ES provided by natural habitats on conserved land have a value proportional to the preserved surface. Such value is stochastic and fluctuates following a geometric Brownian motion. When the parcel is developed then land enters as an input into the production of private goods and/or services (coffee, rubber, soy, palm oil, timber, biofuels, cattle, etc.) destined to a competitive market.

In this context, the Government introduces a land use policy which aims to balance conservation and development. The policy is based on a PES scheme implemented through a conservation contract. Such contract fixes limits to the plot development (i.e. it may be totally or partially developed) and establishes a compensation for land kept aside. In addition to the individual plot set-aside policy, we also consider the possibility that the Government impose a limit on the total clearable forested land in the targeted area.

In this frame, we determine analytically the optimal conversion path and study the impact that different payment schemes may have on the conversion dynamics. Not surprisingly, conversion is postponed if a higher compensation is paid to landholders conserving the entire plot. This is due to the higher opportunity cost of conversion which is higher since it includes the payments implicitly given up converting. Interestingly, we show that, as suggested by Ferraro (2001), a landholder may conserve the entire plot even if only partially compensated for the provided ES. We note that only progressive reductions in the value of ES may induce land clearing. Studying the impact of a limit on the aggregate conversion, we identify two possible scenarios. In fact, depending on the total land surface privately worth to be developed, such limit may be binding or not. If not binding then landholders stop converting land at an aggregate surface smaller than the one targeted by the Government since profits from further land conversion are too low. If binding, on the contrary, further conversion is profitable and then landholders, fearing a restriction in the exercise of the option to convert, may start a conversion run⁶ which rapidly exhausts the forest stock up to the fixed limit.⁷ Comparing first-best and second-best conversion policy we identify the combination of policy parameters leading to a first-best conversion policy.

To assess the temporal performance of the optimal conservation policy and study the impact of increasing uncertainty about future environmental benefits on conversion speed, we derive the long-run average growth rate of deforestation. Interestingly, we show that higher uncertainty over payments, even if it induces conversion postponement in the short-run, increases the average rate of deforestation and reduces expected time for total conversion in the long run.

Finally, we run several numerical simulations based on the well known case of Costa Rica. Firstly, we study the impact of different conservation policies on the optimal forest stock and the expected long-run average rate of deforestation. Second, given a certain initial forest stock, we rank different policies on the basis of long-run average rate of deforestation and expected total conversion time.

The remainder of the paper is organized as follows. In Section 2 the basic set-up for the model is

⁵Among them, see for instance Conrad (1980), Clarke and Reed (1989), Reed (1993), Conrad (1997), Conrad (2000).

⁶In Australia, the Productivity Commission reports evidence of pre-emptive clearing due to the introduction of clearing restrictions (Productivity Commission, 2004). On unintended impacts of public policy see for instance Stavins and Jaffe (1990) showing that, despite an explicit federal conservation policy, 30% of forested wetland conversion in the Mississippi Valley has been induced by federal flood-control projects. In this respect, see also Mæstad (2001) showing how timber trade restrictions may induce an increase in logging.

⁷A similar effect has been firstly noted by Bartolini (1993). In this paper, the author studies decentralized investment decision in a market where a limit on aggregate investment is present.

presented. In Section 3 we study the equilibrium in the conversion strategies and compare first-best and second-best outcomes. In Section 4, we discuss issues related to the PES voluntary participation and contract enforceability. Section 5 is devoted to the derivation of the long-run average rate of conversion. In Section 6 we illustrate our main findings through numerical exercises. Section 7 concludes.

2 A Dynamic Model of Land Conversion

Consider a country where at time period $t \geq 0$ the total land available, L , is allocated as follows:

$$L = A(t) + F(t), \quad \text{with } A(0) = A_0 \geq 0 \quad (1)$$

where $A(t)$ is the surface cultivated and $F(t)$ is the portion still in its pristine natural state covered by a primary forest.⁸

Assume that $F(t)$ is divided into infinitesimally small and homogenous parcels of equal extent held by a multitude of identical risk-neutral landholders.⁹ By normalizing such extent to 1 hectare, $F(t)$ denotes also the number of agents in the economy.¹⁰

Natural habitats provide valuable environmental goods and services at each time period t .¹¹ Let denote by $B(t)$ their per-unit value and assume it randomly fluctuates according to the following geometric Brownian motion:

$$\frac{dB(t)}{B(t)} = \alpha dt + \sigma dz(t), \quad \text{with } B(0) = B_0 \quad (2)$$

where α and σ are respectively the drift and the volatility parameters, and $dz(t)$ is the increment of a Wiener process.¹²

At each t , two competitive and mutually exclusive destinations may be given to forested land: conservation or irreversible development. Once the plot is cleared, the landholder becomes a farmer using land as an input for agricultural production (or commercial forestry).¹³

⁸As in Bulte et al. (2002) A_0 may represent the best land which has been already converted to agriculture.

⁹For the sake of generality we simply refer to landholders. In our model in fact, as quite common in a developing country scenario, the appropriability of values attached to land is not conditional on the existence of a legal entitlement. See Gregersen et al. (2010).

¹⁰None of our results relies on this assumption. In fact, provided that no single agent has significant market power, we can obtain identical results by allowing each agent to own more than one unit of land. See e.g. Baldursson (1998) and Grenadier (2002).

¹¹They may include biodiversity conservation, carbon sequestration, watershed control, provision of scenic beauty for recreational activities and ecotourism, timber and non-timber forest products. See e.g. Conrad (1997), Conrad (2000), Clarke and Reed (1989), Reed (1993), Bulte et al. (2002).

¹²The Brownian motion in (2) is a reasonable approximation for conservation benefits and we share this assumption with most of the existing literature. Conrad (1997, p. 98) considers a geometric Brownian motion for the amenity value as a plausible assumption to capture uncertainty over individual preferences for amenity. Bulte et al. (2002, p.152) point out that "*parameter α can be positive (e.g., reflecting an increasingly important carbon sink function as atmospheric CO2 concentration rises), but it may also be negative (say, due to improvements in combinatorial chemistry that lead to a reduced need for primary genetic material)*". However, this assumption neglects the direct feedback effect that conversion decisions may have on the stochastic process illustrating the dynamic of conservation benefits. See Leroux et al. (2009) for a model where such effect is accounted by letting conservation benefits follow a controlled diffusion process with both drift and volatility depending on the conversion path.

¹³In the following, "landholder" refers to an agent conserving land and "farmer" to an agent cultivating it.

2.1 The Government

ES usually have the nature of public good. To induce their provision we assume that at time period $t = 0$ the Government offers a contract to be accepted on a voluntary basis by each farmer. A compensation equal to $\eta_1 B(t)$ with $\eta_1 \in [0, 1]$ is paid at each time period t if the entire plot is conserved. On the contrary, if the landholder aims to develop his/her parcel, a restriction is imposed in that a portion of the total surface, $0 \leq \lambda \leq 1$, must be conserved.¹⁴ In this case, a payment equal to $\lambda \eta_2 B(t)$ with $\eta_2 \in [0, \eta_1]$ ¹⁵ may be offered to compensate the landholder.¹⁶

In addition, besides λ the Government fixes an upper level \bar{A} on total land conversion. These two limits may be fixed to account for critical ecological thresholds at which, if crossed, the ES provision may dramatically lower or vanish.¹⁷ It is straightforward to see that depending on the magnitude of λ the existence of a ceiling may preclude land development for some landholders. To account for this outcome we denote by $\bar{N} = \frac{\bar{A}}{1-\lambda}$ the number of potential farmers involved in the conversion process and assume $\bar{N} \leq F(0)$.

Our framework is general enough to include different conservation targets such as old-growth forests or habitat surrounding wetlands, marshes, lagoons or by the marine coastline and meet several spatial requirements. For instance, the conservation target may be represented by an area divided into homogenous parcels running along a river or around a lake or a lagoon where, to maintain a significant provision of ecosystem services, a portion of each parcel must be conserved (see figure 1). As stressed by the literature in spatial ecology, the creation of buffer areas, by managing the proximity of human economic activities, is crucial since it guarantees the efficiency of conservation measures in the targeted areas.¹⁸ In this case the conservation program may be induced by implementing a payment contract schedule differentiating for the state of land i.e. totally conserved vs. developed within the restriction enforced through environmental law. However, we are also able to consider the opposite case where the landholder may totally develop his/her plot but an upper limit is fixed on the total extent of land which can be cleared in the region.¹⁹

¹⁴In Brazil, for instance, according to the legal reserve regulation a private owner must keep the 20% (80% in the Amazon) of the surface in the property covered by forest or its native vegetation (Alston and Mueller, 2007). The choice of λ may account for considerations related to habitat fragmentation, critical ecological thresholds, enforcement and transaction costs for the program implementation, etc. Finally, note that our analysis is general enough to include also the case where λ is not imposed but is endogenously set by each landholder. In fact, due for instance to financial constraints limiting the extent of the development project, the landholders may find optimal not to convert the entire plot (Pattanayak et al., 2010).

¹⁵A lower payment rate can be justified on the basis of a less valuable ES provision due to the disturbance, implicitly produced by developing the plot, to the previously intact natural habitat. For instance, one may assume that an unique payment rate η is fixed but that once the plot is developed the per-unit ES value, $B(t)$, is lowered by some $k \in [0, 1]$. It is straightforward to see that by simply setting $\eta_2 = k\eta_1$ our results would still hold.

¹⁶As pointed out by Engel et al. (2008), by internalizing external non-market values from conservation, PES schemes have attracted increasing interest as mechanisms to induce the provision of ES. Consistently, the payment rates, η_1 and η_2 , may be interpreted as the levels of appropriability that the society is willing to guarantee on the value generated by conserving, i.e. $B(t)$ and $\lambda B(t)$ respectively. Finally, note that as η_1 and η_2 are constant then payments also follow a geometric Brownian motion (easily derivable from (2)). However, this is different from the way payments are modelled in Isik and Yang (2004) where they also depend on the fluctuations in the conservation cost opportunity (profit from agriculture, changes in environmental policy, etc.).

¹⁷On ecosystem resilience, threshold effects and conservation policies see Perrings and Pearce (1994). Note that the quality of our results would not change if one characterized \bar{A} as the expected surface at which the Government will impede further land conversion.

¹⁸See for instance Hansen and Rotella (2002) and Hansen and DeFries (2007).

¹⁹This could be the case for an area covered by a tropical forest (Bulte et al., 2002; Leroux et al., 2009), or a protected area where farmers located next to the site may sustainably extract natural resources (Tisdell, 1995; Wells et al., 1992).

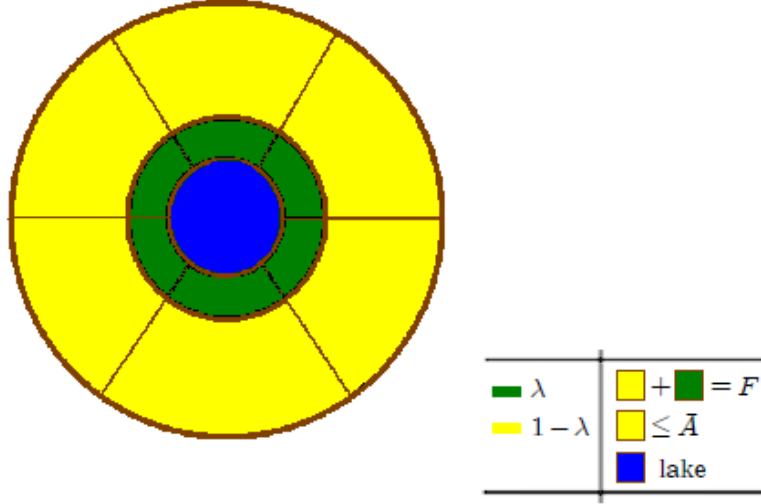


Figure 1: Land conversion with buffer areas

2.2 The Landholders

Developing the parcel is an irreversible action which has a sunk cost, $(1 - \lambda)c$, including cost for clearing and settling land for agriculture.²⁰ Denoting by $A(t)$ the total land developed at time t , the number of farmers must be equal to $N(t) = \frac{A(t)}{1-\lambda}$ and since $1 - \lambda$ is fixed, the conversion dynamic must mirror the variation in the number of farmers, i.e. $dN(t) = \frac{dA(t)}{1-\lambda}$. Therefore, assuming that the extent of each plot is small enough to exclude any potential price-making consideration, we may use either $N(t)$ or $A(t)$ when evaluating the individual decision process.²¹ Competition on the market for agricultural products implies that at each time period t the optimal number of farmers (or the optimal total land developed) is determined by the entry zero profit condition. In addition, since the per-parcel value of services, $B(t)$, makes all agents symmetric.

We assume a constant elasticity demand function for agricultural products $P_A(t) = \delta A(t)^{-\gamma}$ with $\delta > 0$ and $\gamma > 0$. The parameter δ illustrates different states of the demand while $-\gamma$ is the inverse of the demand elasticity.

Now, let's solve for the conversion process taking η_1 , η_2 and λ as exogenously given parameters. Denoting by $P_A(t)$ the marginal return as land is cleared over time, the farmer instantaneous profit function is given by:

$$\pi(A(t), B(t); \bar{A}) = (1 - \lambda)P_A(t) + \lambda\eta_2 B(t) \quad (3)$$

The discounted present value of the benefits accruing over an infinite horizon is given by:²²

$$\begin{aligned} E_0 \left[\int_0^\tau e^{-rt} \eta_1 B(t) dt + \int_\tau^\infty e^{-rt} \pi(A(t), B(t); \bar{A}) dt \right] = \\ = \frac{\eta_1 B_0}{r - \alpha} + E_0 \left[\int_\tau^\infty e^{-r(t-\tau)} \Delta\pi(A(t), B(t); \bar{A}) dt \right] \end{aligned} \quad (4)$$

²⁰Bulte et al., (2002, p. 152) define c as "the marginal land conversion cost". It "may be negative if there is a positive one-time net benefit from logging the site that exceeds the costs of preparing the harvested site for crop production". We also assume, without loss of generality, that the conversion cost is proportional to the surface cleared.

²¹To consider infinitesimally small agents is a standard assumption in infinite horizon models investigating dynamic industry equilibrium under competition. See for instance Jovanovic (1982), Dixit (1989), Hopenhayn (1992), Lambson (1992), Dixit and Pindyck (1994, chp. 8), Bartolini (1993), Caballero and Pindyck (1996), Dosi and Moretto (1992) and Moretto (2008).

²²Note that the expected value is taken accounting for $A(t)$ increasing over time as land is cleared. See Harrison (1985, p. 44).

where r is the constant risk-free interest rate,²³ $\Delta\pi(A(t), B(t); \bar{A}) = (1 - \lambda)P_A(t) + (\lambda\eta_2 - \eta_1)B(t)$ and τ is the stochastic conversion time.

In (4) the first term represents the perpetuity paid by the Government if the parcel is conserved, while the second term represents the extra profit that each landholder may expect if she/he clears the land and becomes a farmer. The extra profit is given by the crop yield sold on the market plus the difference in the payments received by the Government. As soon as the excess profit from land development equals the deforestation cost, the landholder may clear the parcel. This implies that the optimal conversion timing depends only on the second term in (4).

3 The Competitive Equilibrium

Denote by $V(A(t), B(t); \bar{A})$ the value function of an infinitely living farmer.²⁴ By (4), the optimal conversion time, τ , solves the following maximization problem:²⁵

$$V(A, B; \bar{A}) = \max_{\tau} E_0 \left\{ \int_0^{\infty} e^{-rt} [\Delta\pi(A, B; \bar{A}) dt - I_{[t=\tau]}(1 - \lambda)c] dt \right\} \quad (5)$$

where $I_{[t=\tau]}$ is an indicator function stating that at the time of conversion, due to market competition among farmers, the value attached to land conversion must equal the cost of land clearing. In the real option literature the problem we must solve is referred to as "optimal stopping" (Dixit and Pindyck, 1994). The idea is that at any point in time the value of immediate investment (stopping) is compared with the expected value of waiting over the next dt (continuation), given the information available at that point in time (the stock of land developed, A , and the value of the stochastic variable B) and the knowledge of the two processes, i.e. dA and dB . If the initial size of the active farmers is $A \geq A_0$, we expect the converting process to work as follows: for a fixed number of farmers, profits in (3) move stochastically driven only by B . As soon as the per-parcel value of ES reaches a critical level, say $B^*(A)$, development (i.e. entry into the agricultural market) becomes feasible. This implies an increase, dA , in cultivated land and a drop in revenues from agriculture along the demand function $P_A(A)$. The value of services will then continue to move stochastically until the next entry occurs.

Let $V(A, B; \bar{A})$ be twice-differentiable in B , and expand $dV(A, B; \bar{A})$ using Ito's Lemma. Then, in the region of values where no conversion takes place, the solution to (5) must solve the following differential equation:²⁶

$$\begin{aligned} \frac{1}{2}\sigma^2 B^2 V_{BB}(A, B; \bar{A}) + \alpha B V_B(A, B; \bar{A}) - rV(A, B; \bar{A}) + \\ + [(1 - \lambda)\delta A^{-\gamma} + (\lambda\eta_2 - \eta_1)B] = 0 \end{aligned} \quad (6)$$

This is an ordinary differential equation since the number of farmers is constant. Using standard arguments the general solution is (see Dixit and Pindyck, 1994):

$$V(A, B; \bar{A}) = Z_1(A)B^{\beta_1} + Z_2(A)B^{\beta_2} + (1 - \lambda)\frac{\delta A^{-\gamma}}{r} + (\lambda\eta_2 - \eta_1)\frac{B}{r - \alpha} \quad (7)$$

where $1 < \beta_1 < r/\alpha$, $\beta_2 < 0$ are the roots of the characteristic equation $Q(\beta) = \frac{1}{2}\sigma^2\beta(\beta - 1) + \alpha\beta - r = 0$ and Z_1, Z_2 are two constants to be determined.

²³The introduction of risk aversion does not change the results since the analysis can be developed under a risk-neutral probability measure for $B(t)$. See Cox and Ross (1976) for further details.

²⁴As we show in the appendix (A.2), the problem can be equivalently solved considering a landholder evaluating the option to develop.

²⁵In the following we will drop the time subscript for notational convenience.

²⁶In our setting the (competitive) equilibrium bounding the profit process for each farmer can be constructed as a symmetric Nash equilibrium in entry strategies. By the infinite divisibility of F , the equilibrium can be determined by simply looking at the single landholder clearing policy which is defined ignoring the competitors' entry decisions (see Leahy, 1993). Consider a short interval dt where no conversion takes place. Over this interval A is constant and the farmer holds an asset paying $\Delta\pi(A, B; \bar{A})dt$ as cash flow and $E[dV(A, B; \bar{A})]$ as capital gain. If the farmer is active then the cash flow and the expected capital gain must equal the risk-neutral return, that is $rV(A, B; \bar{A})dt = \Delta\pi(A, B; \bar{A})dt + E[dV(A, B; \bar{A})]$.

To determine the optimal conversion threshold, $B^*(A)$, the landholder must consider benefits and costs attached to conversion. According to (7), the profit accruing from the crop yield, $(1 - \lambda)\frac{\delta A^{-\gamma}}{r}$, is counter-balanced by the difference in the payments, $(\lambda\eta_2 - \eta_1)\frac{B}{r - \alpha}$, received for conservation. In addition, note that as landholders convert land and become farmers profit from agriculture decreases. This negative effect on the value of converted land is accounted for in (7) by the second term ($Z_2(A) \leq 0$ for $A \leq \bar{A}$). In fact, since by assumption $\eta_1 \geq \eta_2$ implies $\eta_1 > \lambda\eta_2$ then only an expected reduction in B can induce conversion.²⁷ Since $\beta_1 > 0$ then to keep $V(A, B; \bar{A})$ finite we must drop the first term by setting $Z_1 = 0$, i.e. $\lim_{B \rightarrow \infty} V(A, B; \bar{A}) = 0$. Hence, (7) reduces to:

$$V(A, B; \bar{A}) = Z_2(A)B^{\beta_2} + (1 - \lambda)\frac{\delta A^{-\gamma}}{r} + (\lambda\eta_2 - \eta_1)\frac{B}{r - \alpha} \quad (8)$$

To determine $Z_2(A)$ and $B^*(A)$ some suitable boundary conditions on (8) are required. First, development by increasing the number of competing farmers in the market keeps the value of being an active farmer below $(1 - \lambda)c$. Second, marginal rents for an active farmer must be null at $B^*(A)$. These considerations can be formalized by the following proposition:

Proposition 1 *Provided that each agent rationally forecasts the future dynamics of the market for agricultural goods for land to be converted, the following condition must hold*

$$V(A, B^*(A); \bar{A}) = (1 - \lambda)c \quad (9)$$

where the conversion rule is

(i) if $\hat{A} \leq \bar{A}$ then

$$B^*(A) = \frac{\beta_2}{\beta_2 - 1} (r - \alpha) \Psi \left[\left(\frac{\hat{A}}{A} \right)^\gamma - 1 \right] c \quad \text{for } A_0 < A \leq \hat{A} \quad (10)$$

(ii) if $\hat{A} > \bar{A}$ then

$$B^*(A) = \begin{cases} \frac{\beta_2}{\beta_2 - 1} (r - \alpha) \Psi \left[\left(\frac{\hat{A}}{A} \right)^\gamma - 1 \right] c, & \text{for } A_0 < A \leq A^+ \quad (\text{a}) \\ (r - \alpha) \Psi \left[\left(\frac{\hat{A}}{A} \right)^\gamma - 1 \right] c, & \text{for } A^+ < A \leq \bar{A} \quad (\text{b}) \end{cases} \quad (10 \text{ bis})$$

where

$$\hat{A} = \left(\frac{\delta}{rc} \right)^{1/\gamma}, \quad A^+ = \left[\frac{(\beta_2 - 1)\bar{A}^{-\gamma} + \hat{A}^{-\gamma}}{\beta_2} \right]^{-\frac{1}{\gamma}} \quad \text{and} \quad \Psi = \frac{1 - \lambda}{\eta_1 - \lambda\eta_2}. \quad (10\text{ter})$$

Proof. See appendix A.1. ■

In Proposition 1, we denote by \hat{A} the last parcel for which conversion makes economic sense (i.e. $\frac{\delta}{r}\hat{A}^{-\gamma} - c = 0$) and by A^+ the surface at which a conversion run starts (i.e. $B^*(A^+) = B^*(\bar{A})$).

Note that for conversion to be optimal, the dynamic zero profit condition in (9) must hold at the threshold, $B^*(A)$. By rearranging (9) we obtain

$$Z_2(A)B^*(A)^{\beta_2} + (1 - \lambda)\frac{\delta A^{-\gamma}}{r} + \lambda\eta_2\frac{B^*(A)}{r - \alpha} = (1 - \lambda)c + \eta_1\frac{B^*(A)}{r - \alpha}$$

This condition says that benefits from becoming a farmer must equal the opportunity cost of conversion, i.e. the cost of land clearing plus the payment perpetuity which is implicitly given up, as stated in equation (4), by converting.

By Proposition 1 the whole conversion dynamics are characterized in terms of B . Since the agent's size is infinitesimal, the trigger $B^*(A)$ must be a decreasing function of A . In both figure 2 and 3 conservation is optimal in the region above the curve. In fact, in this region, B is high enough to deter conversion and each landholder conserves up to the time where B driven by (2) drops to $B^*(A)$. Then, as B crosses

²⁷Di Corato et al. (2010) show that by relaxing such assumption also an expected increase in B may induce land conversion.

$B^*(A)$ from above, a discrete mass of landholders will enter the agricultural market developing (part of) their land. Since higher competition reduces profits from agriculture, entries take place until conditions for conservation are restored ($B > B^*(A)$). Further, Proposition 1 also shows that even if the ES provided by a targeted ecosystem is not entirely compensated for, i.e. $\eta_1 \leq 1$, the Government may still be able to induce landholders to conserve their plot.²⁸

Depending on \bar{A} , we obtain two different scenarios (see figure 2 and 3):

- (1) if $\hat{A} \leq \bar{A}$, the conversion process stops at \hat{A} . This in turn implies that the surface, $\bar{A} - \hat{A} \geq 0$, is conserved forever at a total cost equal to $\eta_1 \frac{B}{r-\alpha} (\bar{A} - \hat{A})$.

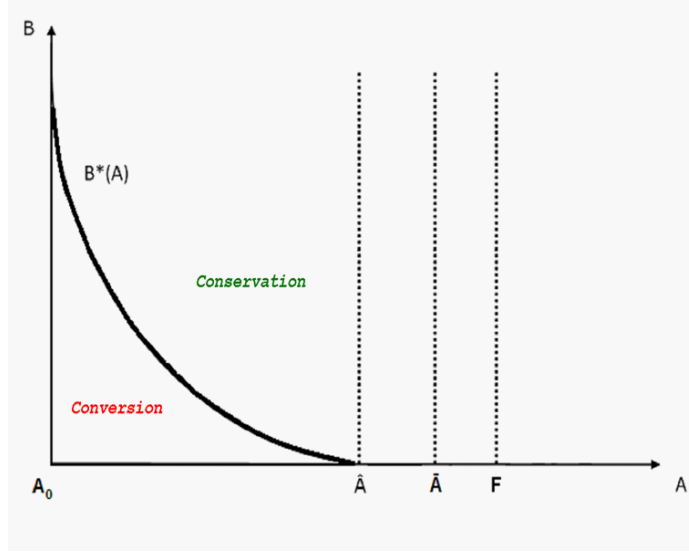


Figure 2: Optimal conversion threshold with $\hat{A} \leq \bar{A}$

- (2) if $\hat{A} > \bar{A}$, land is converted smoothly up to A^+ following the curve (10 bis(a)). If the surface of cultivated land falls within the interval $A^+ \leq A \leq \bar{A}$, when B hits the threshold $B^*(A)$, the landholders start a run for conversion up to \bar{A} . Unlike the previous case, here the limit imposed by the Government binds and restricts conversion on a surface, $\bar{A} - \hat{A} > 0$ where development would be profitable from the landholder's viewpoint. The intuition behind this result is immediate if we take a backward perspective. When the limit imposed by the Government \bar{A} is reached, then it must be $Z_2(\bar{A}) = 0$ since no new entry may occur. Hence, condition (9) reduces to $V(\bar{A}, B^*(\bar{A}); \bar{A}) = (1 - \lambda) \frac{\delta \bar{A}^{-\gamma}}{r} + (\lambda \eta_2 - \eta_1) \frac{B^*(\bar{A})}{r - \alpha} = (1 - \lambda)c$ from which we obtain (10bis (b)) as optimal trigger. This implies that at \bar{A} marginal rents induced by future reduction in B are not null, i.e. $V_B(\bar{A}, B; \bar{A}) < 0$, and they would be entirely captured by market incumbents. Since each single landholder realizes the benefit from marginally anticipating his entry decision, then an entry run occurs to avoid the restriction imposed by the Government. However, by rushing, the rent attached to information on market profitability, collectable by waiting, vanishes. Therefore there will be a land extent (i.e. a number of farmers), $A^+ < \bar{A}$, such that for $A < A^+$ no landholder finds it convenient to rush since the marginal advantages from a future reduction in B are lower than the option value lost.²⁹ Note also that, as A^+ is given by $B^*(A^+) = B^*(\bar{A})$, the threshold in (10bis), triggering the run, results in the traditional NPV break-even rule (see Appendix A.1).³⁰

²⁸This result is in line with Ferraro (2001, p. 997) where the author states that conservation practitioners "may also find that they do not need to make payments for an entire targeted ecosystem to achieve their objectives. They need to include only "just enough" of the ecosystem to make it unlikely, given current economic conditions, infrastructure, and enforcement levels, that anyone would convert the remaining area to other uses".

²⁹This means the A^+ th is the last landholder for whom $V_B(A^+, B^*(A^+); \bar{A}) = 0$.

³⁰In Bartolini (1993) a similar result is obtained. Under linear adjustment costs and stochastic returns, investment cost is constant up to the investment limit where it becomes infinite. As a reaction to this external effect, recurrent runs may occur under competition as aggregate investment approaches the ceiling. See also Moretto (2008).

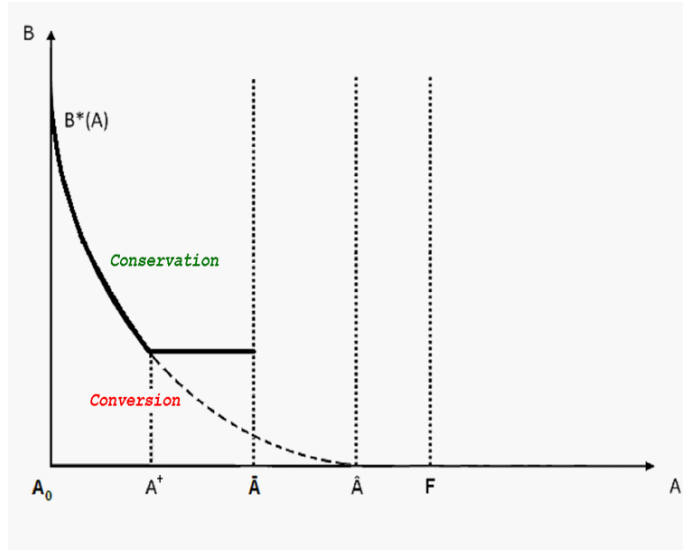


Figure 3: Optimal conversion threshold with $\hat{A} > \bar{A}$

3.1 Comparative statics

As shown in table 1 the definition of the last plot, \hat{A} , which is worth converting, depends on parameters regulating the demand for agricultural goods, the interest rate and the land unit conversion cost. A higher δ illustrating a higher demand for agricultural products and/or a more rigid demand moves \hat{A} forward since higher profits support the conversion for a larger land surface. Similarly, as $c \rightarrow 0$, all the available land will be cultivated ($\hat{A} \rightarrow \bar{A}$). With a higher r future returns from agriculture become relatively lower with respect to the cost of clearing land and land conversion is less attractive.

	\hat{A}	B^*
δ	> 0	≥ 0
c	< 0	≤ 0
r	< 0	≤ 0
γ	< 0	≤ 0
A	-	≤ 0
σ^2	-	≤ 0
η_1	-	≤ 0
η_2	-	≥ 0
λ	-	< 0

Table 1: Comparative statics on \hat{A} and $B^*(A)$

In table 1, we provide some comparative statics illustrating the effect that changes in the exogenous parameters have on the threshold level $B^*(A)$. Changes in an exogenous parameter, whenever increasing (decreasing) conversion benefits with respect to conservation benefits, redefine, by moving upward (downward) the boundary $B^*(A)$, the conversion and conservation regions. In this light, for instance, to a higher δ corresponds higher profits from agriculture and thus a higher $B^*(A)$ and a larger conversion region. The same effect is also produced by a relatively more inelastic demand. On the contrary, the opposite occurs as c increases since a higher conversion cost decreases net conversion benefits. With an increase in the interest

rate, exercise of the option to convert should be anticipated but this effect is too weak to prevail over the effect that a higher r has on the opportunity cost of conversion. Studying the effect of volatility, σ , and of growth parameter, α , the sign of the derivatives is in line with the standard insight in the real options literature. An increase in the growth rate and volatility of B determines postponed exercise of the option to convert. This can be explained by the need to reduce the regret of taking an irreversible decision under uncertainty. Since the cost of this decision is growing at a faster rate and there is uncertainty about its magnitude, waiting to collect information about future prospects is a sensible strategy.

In figure 4 and 5 we illustrate the impact on the conversion threshold of a change in α and σ when $\bar{A} < \hat{A}$, respectively.³¹ The comparative statics above are confirmed. As α increases the land development run is postponed. The interpretation is straightforward. In fact, a higher expected growth in the value of ES, by raising the opportunity cost of conversion, makes land development less attractive. This in turn reduces the regret for being halted by the ceiling \bar{A} on land development imposed by the government. On the contrary, as σ soars the run is anticipated. This effect may seem counterintuitive since a higher σ lowers the conversion barrier. However, by the convexity of $B^*(A)$, as the land is developed a decrease of the level of B induces conversion on larger surfaces. Hence, since a higher volatility of B increases the probability of reaching the conversion barrier then landowners start running earlier in that it becomes more likely that the ceiling \bar{A} may be binding.

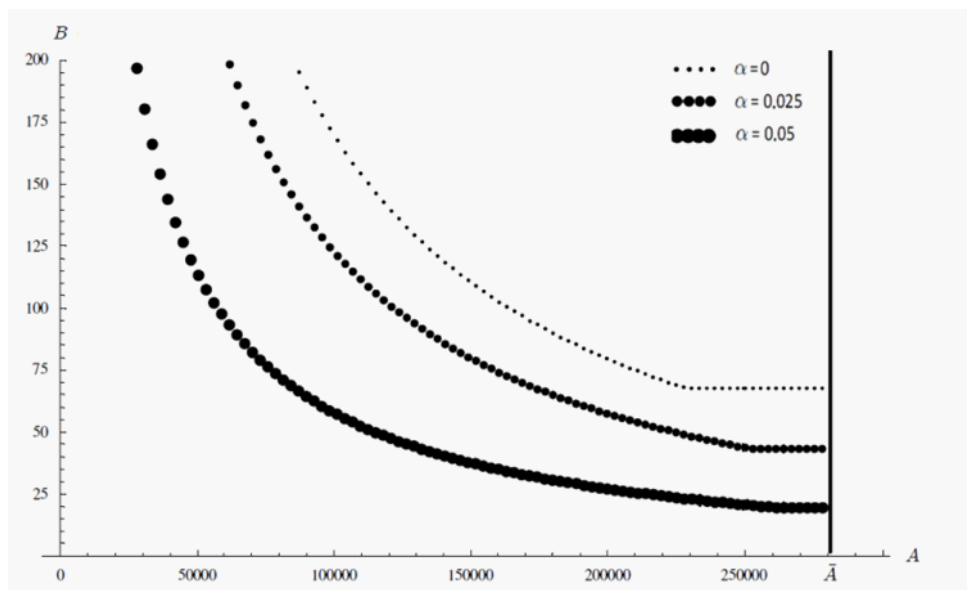


Figure 4: Optimal conversion barriers for $r = 0.07$, $\sigma = 0.1$,
 $c = 500$ and $\bar{A} = 281375$

³¹Figure 4 and 5 are obtained using the calibration adopted for the numerical exercise developed in Section 6.

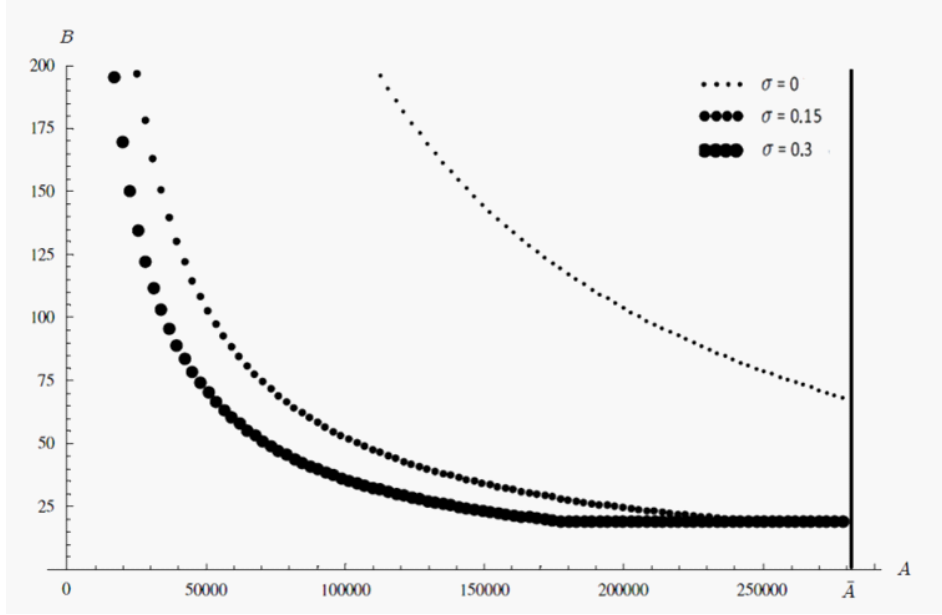


Figure 5: Optimal conversion barriers for $r = 0.07$, $\alpha = 0.05$,
 $c = 500$ and $\bar{A} = 281375$

Let's consider now the conservation policy parameters. As expected, an increase in η_1 pushes the barrier downward since it makes it more profitable to conserve the plot and keep open the option to convert. In line with this result, the barrier responds in the opposite way to an increase in η_2 which implicitly provides an incentive to conversion. Changes in λ have a monotonic effect. A higher λ defines a stricter requirement on development that may push the barrier downward for two reasons. First, a lower return from agriculture since less land is cultivated which is, however, balanced by a lower cost for clearing land, and second, since $\eta_1 > \eta_2$ then a higher payment on the marginal unit which the farmer is required to set aside is guaranteed if the plot is totally conserved. By using the second consideration the optimal conversion rule must be clearly independent on λ when $\eta_1 = \eta_2$.

These considerations mostly hold for both (10) and (10 bis). Clearly, over the interval $A^+ < A \leq \bar{A}$ since the option multiple, $\frac{\beta_2}{\beta_2 - 1}$, drops out, the barrier $B^*(A)$ is not affected by σ . The derivative with respect to the benefit drift α maintains the sign in table 1 while the comparative statics on r reveals:

$$\frac{\partial B^*(A)}{\partial r} = \begin{cases} > 0 \text{ for } r < \alpha \left(\frac{\hat{A}}{A}\right)^\gamma \\ \leq 0 \text{ for } r \geq \alpha \left(\frac{\hat{A}}{A}\right)^\gamma \end{cases} \quad \text{for } A^+ < A \leq \bar{A}$$

Finally, since by (10bis) the same level of B triggers the entry of a positive mass of landholders, i.e. $B^*(A^+) = B^*(\bar{A})$, it is worth highlighting that the surface at which the conversion rush starts (A^+) is independent of the definition of η_1 , η_2 and λ . The Government policy may either speed up or slow down the conversion dynamic but it cannot alter A^+ which depends only on the choice of \bar{A} with respect to \hat{A} . Note that $\partial A^+ / \partial \bar{A} > 0$ which reasonably means that as $\bar{A} \rightarrow \hat{A}$ the run would be triggered only by a relatively lower level for B . In other words, since in expected terms a higher \bar{A} implies a less strict threat of being regulated, then landholders are not willing to give up information rents collectable by waiting. Not surprisingly, $\partial A^+ / \partial \hat{A} < 0$. A lower \hat{A} implies a faster drop in the profit from agriculture as A increases and then a lower incentive for the conversion run.

3.2 First vs second-best policies

A natural benchmark for our analysis is represented by the socially optimal conversion policy. Since a social planner does not need to impose the individual restriction λ , its optimal strategy can be obtained from (10)

by simply setting $\eta_1 = 1$ and $\lambda = 0$ (i.e. $\Psi = 1$). That is³²

$$B^{FB}(A) = \frac{\beta_2}{\beta_2 - 1} (r - \alpha) \left[\left(\frac{\hat{A}}{A} \right)^\gamma - 1 \right] c \quad \text{for } A_0 < A \leq \hat{A} \quad (11)$$

Note that for $\hat{A} \leq \bar{A}$ this is the first-best conversion strategy in Bulte et al. (2002). In our model, it is immediate to show that several combinations of the second-best tools η_1 , η_2 and λ result in $\Psi = 1$ and lead to the first-best conversion policy. In particular, explicating such combinations in terms of η_2 , the first-best outcome correspond to the relationship $\eta_2 = 1 - \frac{1-\eta_1}{\lambda}$. However, we observe that this result would not hold when $\hat{A} > \bar{A}$. In this case, even if the triple $(\eta_1, \eta_2, \lambda)$ is such that $\Psi = 1$ the first and second-best conversion policies would overlap only up to A^+ . In fact, once reached the level A^+ the second-best land clearing process, due to the start of a conversion run, accelerates and rapidly exhausts the available forest stock.

Out of the first-best optimal conversion path ($\Psi \neq 1$) the two following scenarios may arise (see figures 6 and 7):

$$\begin{cases} B^{FB} < B^*(A) & \text{for } \eta_2 > 1 - \frac{1-\eta_1}{\lambda} & \text{(a)} \\ B^{FB} > B^*(A) & \text{otherwise} & \text{(b)} \end{cases} \quad (11 \text{ bis})$$

In figure 6 the area below the full line is the set of feasible payment rates ($0 \leq \eta_2 \leq \eta_1$) while the dotted line represents the combination of policy parameters leading to a first-best conversion policy for any given λ ($\eta_2 = 1 - \frac{1-\eta_1}{\lambda}$). The feasible area is split in two regions where depending on the triple $(\eta_1, \eta_2, \lambda)$, the second-best conversion process may be in expected terms faster ($\Psi > 1$: case (a)) or slower ($\Psi < 1$: case (b)) than the first-best one.

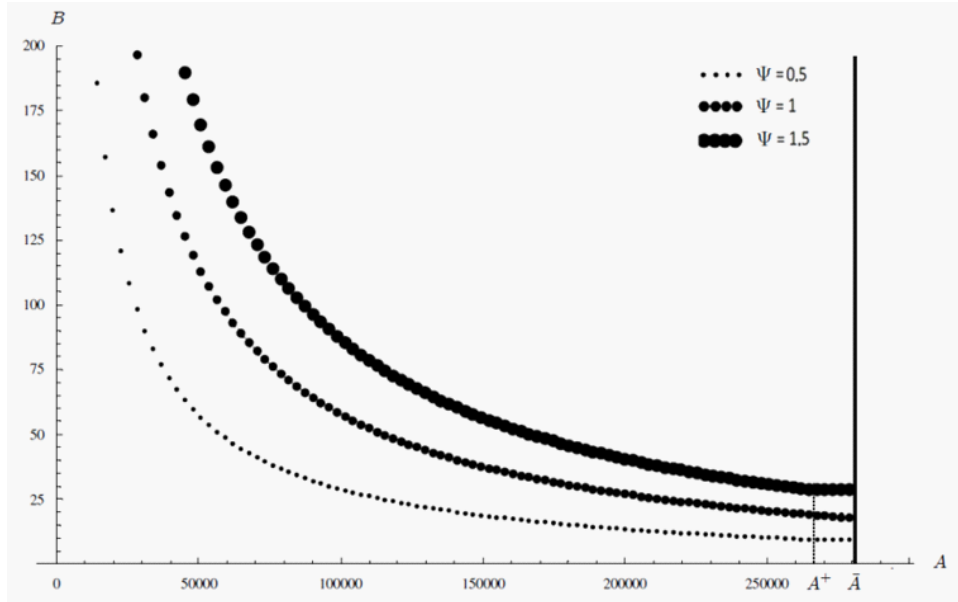


Figure 6: First-best vs. second-best policies for $r = 0.07$, $\alpha = 0.05$, $\sigma = 0.1$, $c = 500$ and $\bar{A} = 281375$

It is immediate to note that

Corollary 1

- a) For $\eta_1 \leq 1 - \lambda$ the second-best conversion process can never be slower than in first-best.
- b) As $\lambda \rightarrow 0$ then the region where $B^{FB} > B^*(A)$ shrinks no matters the level of η_2 .

³²In other words, a competitive equilibrium evolves as maximizing solution for the expected present value of social welfare in the form of consumer surplus (Lucas and Prescott, 1971; Dixit and Pindyck, 1994, ch.9).

The first result (a) holds even when the Government, to deter development, expropriates the portion λ without any compensation ($\eta_2 = 0$). Finally, result (b) suggests the use of higher η_1 or lower η_2 to contrast the effect of a less strict set-aside requirement, λ . The opposite considerations can be formulated for $\lambda \rightarrow 1$.

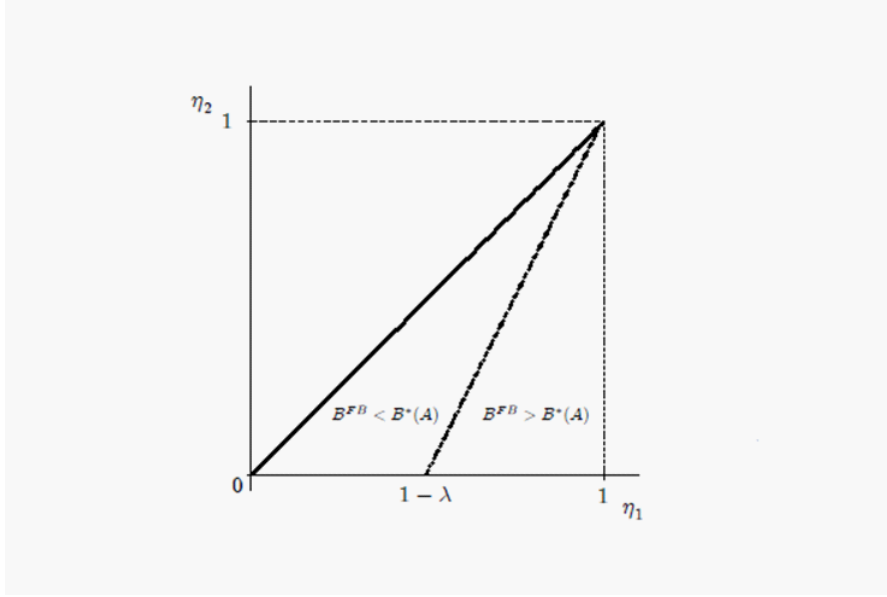


Figure 7: First-best vs. second-best policies

4 Voluntary participation or contract enforceability?

Once the optimal conversion rules have been determined, we focus in this section on the issue of voluntary participation which is a crucial aspect in a PES scheme (Wunder, 2005). In this respect, two elements must be considered. First, the dynamic of the whole conversion process involving all the landholders who enrolled under the conservation program. Second, the restrictions on land development that the Government may wish to impose in the form of takings on landholders not entering the conservation program.³³

A conservation contract may be accepted on a voluntary basis only if each landholder is better-off signing it than not. As it can be easily seen, the acceptance will crucially depend on the expectation concerning the ability of the Government to impose a $\lambda > 0$ to landholder not enrolling under the PES scheme. Let's formalize this consideration assuming that no compensation is paid if a taking occurs. Since by Proposition 1 the conversion is optimal at $B^*(A)$ then an infinitely living landholder signs the contract if and only if:

$$\frac{\eta_1}{r - \alpha} B^*(A) + V(A, B^*(A); \bar{A}) \geq E_t \left[\int_t^\infty e^{-r(s-t)} (1 - \theta\lambda) \delta A(s)^{-\gamma} ds \right] \quad (12)$$

where $\theta \in [0, 1]$ is the probability of regulation, i.e. the restriction λ holds also for landholders not signing the contract. In (12) the LHS describes the position of a landholder within the program while on the RHS we have the expected present value for a landholder not accepting the contract and developing land at time t . Note that in the last case the conversion option is exercised as soon as the expected cost of conversion, $(1 - \theta\lambda)c$, equals the expected benefit from conversion. Rearranging (12) yields:

$$\frac{\eta_1}{r - \alpha} B^*(A) + (1 - \lambda)c \geq (1 - \theta\lambda)c \quad (13)$$

³³Although most of the PES programs in developing countries were introduced as quid pro quo for legal restrictions on land clearing, there are no specific contract conditions preventing the landholder from clearing the area enrolled under the program (Pagiola, 2008, p. 717). In principle, sanctions may apply. For instance, in the PSA (Pagos por Servicios Ambientales) program in Costa Rica, payments received plus interest should be returned by the landholders exiting the scheme (FONAFIFO, 2007). However, in a developing country context, economic and political costs may reduce the enforcement of such sanction.

which holds if

$$\eta_1 B^*(A) - \lambda(1 - \theta)(r - \alpha)c \geq 0$$

where $(r - \alpha)c$ is the annualized conversion cost. Depending on the parameters this condition may not hold for some A . Note in fact that since $B^*(A)$ is a decreasing function of A then (13) implies that:

Proposition 2 *If $\theta \in [0, 1)$ then contract acceptance can be voluntary for some but not all the landholders in the conservation program.*

Proof. Straightforward from Proposition 1. ■

Segerson and Miceli (1998) show that if the probability of future regulation is positive then a voluntary agreement can always be reached. By Proposition 2 we show that this result does not hold in our frame. In fact, uncertainty about future regulation does not allow capturing of all the agents who can be potentially regulated. A similar result is obtained by Langpap and Wu (2004) in a regulator-landowner two-period model for conservation decisions under uncertainty and irreversibility. In their paper, since contract pay-offs are uncertain and signing is an irreversible decision, under certain conditions a landholder may not accept it to stay flexible. Unlike them, we show that under the same threat of regulation a contract can be voluntarily signed by some landholders and not by others. Not surprisingly, imposing by contract constraints on land development reduces flexibility and discourages voluntary participation. Clearly, due to decreasing profit from agriculture, this holds for some landholders but not for all since entering the conservation program becomes more attractive as land is progressively cleared.

Summing up, the voluntary participation crucially depends on the likelihood of takings but also on the magnitude of the compensation payment which a court may impose. In fact, needless to say, if takings can be compensated, then the requirement for contract acceptance becomes more stringent and it is more difficult to sustain agreements on a voluntary basis.³⁴

5 The long-run average rate of forest conversion

We have shown above that even if not entirely compensated ($\eta_1 \leq 1$) landholders may still conserve their plot in its pristine state. However, their "inertia" addresses only "statically" the conservation/development dilemma since they will develop their plots as soon as it will become profitable. Hence, in this section we focus on the temporal implications of the optimal conversion policy, i.e. how long it takes to clear the target surface \bar{A} , and on the impact of increasing uncertainty about future environmental benefits, B , and conversion cost, c , on conversion speed. As main instrument for this analysis, in the following lines we derive a long-run average growth rate of forest conversion (see A.3 and A.4 in the Appendix).

Let's consider the case where $\hat{A} \leq \bar{A}$. This represents the more interesting case since the analysis below remains valid also for the opposite case over the range $A < A^+$. Note in fact that for $A \geq A^+$ the long-run rate of reforestation must obviously tend to infinity due to the conversion run. Rearranging relations (10) yields:

$$\xi = \frac{\beta_2}{\beta_2 - 1} (1 - \lambda) \frac{P_A(A)}{r} - \frac{\eta_1 - \lambda\eta_2}{r - \alpha} B \quad \text{for } \xi < \hat{\xi} \quad (14)$$

where ξ indicates a regulated process in the sense of Harrison (1985, chp. 2) with $\hat{\xi} = \frac{\beta_2}{\beta_2 - 1} (1 - \lambda) c$ as upper reflecting barrier.

The first term on the RHS of (14) represents the expected discounted profit from the cultivation of land conditional on the number of farmers remaining constant. The multiple $\frac{\beta_2}{\beta_2 - 1} < 1$ accounts for the presence of uncertainty and irreversibility. The second term is the expected discounted flow of payments implicitly given up by developing land net of the payments for conservation paid for setting aside λ as required by the Government. When a reduction of B drives ξ upward toward $\hat{\xi}$ then some landholders may find profitable land conversion. New entries in the market, however, determine a drop along $P_A(A)$ which by balancing for the effect of B prevents ξ from rising above $\hat{\xi}$. It follows that since entry is instantaneous then the rate of deforestation is infinite at $\hat{\xi}$.³⁵ Conversely, if $\xi < \hat{\xi}$ the level of B is high enough to support conservation, no

³⁴On compensation and land taking see Adler (2008).

³⁵The fact that at $\hat{\xi}$ the rate of conversion is infinite follows from the non-differentiability of B and then of A with respect to the time t (see Harrison, 1985; Dixit, 1993).

entries occur and consequently the deforestation rate is null. Hence, the reflecting barrier $\hat{\xi}$ does not generate a finite rate of deforestation over time but long periods of inaction followed by short periods of rapid bursts of land conversion.

However, if a steady state distribution for ξ exists within the range $(-\infty, \hat{\xi})$ then it would be always possible to obtain the corresponding marginal distribution for A . This in turn would allow us to determine the long-run average growth rate of forest conversion. Note that since A and B enter additively in (14) the derivation of a steady-state distribution for A is not straightforward. After some tedious algebra, in the appendix we show that:

Proposition 3 *For any initial condition (\tilde{B}, \tilde{A}) such that $\xi(\tilde{B}, \tilde{A}) = \hat{\xi}$ then relations (10) and (10bis) can be approximated as follows:*

$$\frac{A}{\tilde{A}} \simeq \left(\frac{B}{\tilde{B}}\right)^{-\frac{1}{\gamma}} \left[1 - \left(\frac{\tilde{A}}{A}\right)^\gamma\right] \quad (15a)$$

Then, denoting by $\frac{1}{dt}E(d \ln A)$ the measure of the expected long-run growth rate of forest conversion it can be approximated by:

$$\frac{1}{dt}E[d \ln A] \simeq \begin{cases} -\frac{\alpha - \frac{1}{2}\sigma^2}{\gamma} \left[1 - \left(\frac{\tilde{A}}{A}\right)^\gamma\right] & \text{for } \alpha < \frac{1}{2}\sigma^2 \\ 0 & \text{for } \alpha \geq \frac{1}{2}\sigma^2 \end{cases} \quad (15b)$$

where $A_0 \leq \tilde{A} < \hat{A}$ and $\hat{A} = \left(\frac{\delta}{rc}\right)^{1/\gamma}$.

Proof. See Appendix A.4. ■

Thus, if \tilde{B} is the current value of ES and, by (10), \tilde{A} is the corresponding current optimal surface of converted land, the expression in (15b) is the best guess for the average rate at which the forested surface, $\tilde{A} - \hat{A}$, is cleared. Remember that if $\tilde{A} > \hat{A}$ then the deforestation rate is null since $\frac{\delta}{r}A^{-\gamma} < c$ for $\hat{A} < A \leq \tilde{A}$.

It is straightforward to verify that the rate in (15b) is increasing in the volatility of future payments for $\alpha < \frac{1}{2}\sigma^2$. Although at a first glance this result may seem counterintuitive, it follows from the distribution of the log-normal process ξ with an upper reflecting barrier at $\hat{\xi}$. A higher volatility has two distinct effects. First, it pushes the barrier $\hat{\xi}$ downward; second, by increasing the positive skewness of the distribution of ξ , it raises the probability of the barrier being reached.³⁶ Both effects induce a higher rate of deforestation in both the short-run and long-run. On the contrary for $\alpha \geq \frac{1}{2}\sigma^2$ the process ξ drives away from $\hat{\xi}$ and the rate falls to zero.

Furthermore, the rate in (15b) is decreasing in c . The conversion cost has two opposite effects on the expected land clearing speed. The first prevailing effect is immediate and due to the direct braking impact of a more costly decision. The second is more subtle. Since future land clearing will be triggered by a decreasing B then, by delaying conversion, to a higher c corresponds a lower conversion opportunity cost, $(\eta_1 - \lambda\eta_2)B$, in the future.

Finally, since as $c \rightarrow 0$ then $\left(\frac{\tilde{A}}{A}\right)^\gamma \rightarrow 0$, by (15b) it is also immediate to note that:³⁷

Corollary 2

When $c = 0$ the impact of the Government conservation policies on the long-run deforestation rate vanishes. The long-run deforestation rate depends only on the dynamic of B (i.e. α, σ^2), and the economic profitability of land development (i.e. γ).

This result makes sense. Since land development comes at no cost (i.e. the conversion opportunity cost results extremely low), and it is, depending on the level of B , profitable over a vast land surface the Government policies are completely neutralized in the long-run.

³⁶We show in appendix A.5 that to a higher σ corresponds a higher probability of hitting $\hat{\xi}$ and thus a higher long run average deforestation rate.

³⁷Comparable results are obtained by Dixit and Pindyck (1994, pp. 372-373) and Hartman and Hendrickson (2002) when deriving the long-run average growth rate of investment.

6 The Costa Rica case study

In this section we provide a numerical exercise to illustrate our findings. We calibrate the model to fit the characteristics of the Area de Conservación Tortuguero (ACTo).³⁸ This is a territorial unit which covers about 355375 hectares by including the cantones of Guacimo and Pococi, a portion of the canton of Sarapiquí and the province of Limón. In administrative terms, the ACTo is the regional office of the Sistema Nacional de Áreas de Conservación (SINAC), a public body in charge for the sustainable exploitation of forest resources and the conservation of national natural forests. Currently, as reported by Calvo (2008, p. 11), 148000 hectares of the total surface are still forested³⁹ while in the remainder, i.e. 207375 hectares, economic activities, such as agriculture, ranching and forestry, have been undertaken.

In our calculations, we set the following values for the parameters:

1. The extent of the original forested area, F , is 355375 hectares. The currently converted portion is equal to $A_0 = 207375$ hectares.⁴⁰ We assume that the government allows the development of the 50% of the remaining land, i.e. 74000 hectares. This implies that forest conversion should be halted at $\bar{A} = 281375$.
2. The annual value of ES, \tilde{B} , is equal to $\$75/ha$ when we only account for the forest production function, i.e. sustainable exploitation of timber and non-timber forest products and sustainable ecotourism. Otherwise, to include regulatory and habitat functions, we set it equal to $\$200/ha$.⁴¹ To study the impact of its trend and volatility on forest conversion dynamics, we let α take values 0, 0.025, and 0.05 and let σ vary within the interval $[0, 0.35]$.
3. The ACTo belongs to the Atlantic zone of Costa Rica targeted by Bulte et al. (2002). Consistently, in order to draw our demand for agricultural products, we borrow from their study the estimated parameters, $\delta = \$6990062$ (in 1998 US\$) and $\gamma = 0.887$.
4. A 7% risk free interest rate is assumed ($r = 0.07$). Finally, to capture the effect of conversion costs on deforestation and land conversion runs we will consider different levels of costly deforestation, $c = [0, 500, 1500]$.⁴²

In the following, we first present an analysis of first-best conversion dynamics. Then, once discussed the effect of relevant parameters, we illustrate the implications of second-best policies on optimal forest stocks and deforestation rates under different scenarios. In the tables below we provide the optimal forest stock which should be held, $\bar{A} - \hat{A}$, and the average deforestation rate at which such stock should be optimally exhausted in the long-run. Note that in our calculations the deforestation rate may be null in two cases. First, trivially, when the optimal forest stock, $\bar{A} - \hat{A}$, is completely exhausted and second, when the expected fluctuation of B induces inertia, i.e. $\alpha \geq \frac{1}{2}\sigma^2$. We will distinguish between them using 0 for the former and a dash for the latter.

6.1 Optimal forest stock and long-run average rate of deforestation under first-best policy

Suppose for the moment that the social planner may count on the total pristine forested surface of 355375 hectares and that the ceiling on forest conversion is $\bar{A} = 281375$. As shown above, the first-best optimal conversion policy can be easily obtained by setting $\eta_1 = 1$ and $\lambda = 0$ ($\Psi = 1$). By plugging the assumed level for \tilde{B} in equation (10) we determine the corresponding optimal converted land surface, $\hat{A} = A(\tilde{B})$, and by subtracting it from \bar{A} , the optimal forest stock. The long-run rate at which such stock should be exploited is instead determined by plugging \hat{A} into (15b).

Results in tables 2 and 3 confirms the comparative statics previously presented. As expected, higher conversion costs induce larger optimal forest stocks and lower long-run average deforestation rates. We

³⁸Further details are available at http://www.acto.go.cr/general_info.php and <http://www.sinac.go.cr/areassilvestres.php>.

³⁹The total forested area includes 100000 hectares under protection and 48000 hectares without.

⁴⁰We simply subtract from 355375 hectares the surface of 148000 hectares that, up to Calvo (2008, p. 11), is still forested.

⁴¹See Bulte et al. (2002, pp. 154-155).

⁴²Bulte et al. (2002) and Leroux et al. (2009) use $c = 0$ assuming that the revenue from timber sales offsets the clearing costs.

observe the same effect for higher level of \tilde{B} . This is not surprising since the opportunity cost of conversion increases with \tilde{B} .

$\tilde{B}=75$		$\tilde{A}-\tilde{A}$			<i>Deforestation rate ($\tilde{A} \rightarrow \tilde{A}$)</i>		
		$\alpha = 0$	$\alpha = 0.025$	$\alpha = 0.05$	$\alpha = 0$	$\alpha = 0.025$	$\alpha = 0.05$
$\sigma =$	0	0	38058	183849	0	-	-
	0.05	0	50165	186501	0	-	-
	0.1	0	75586	193478	0	-	-
	0.15	25806	102615	202736	0.0127	-	-
	0.2	60672	127330	212510	0.0225	-	-
	0.25	90320	148859	221764	0.0352	0.0070	-
	0.3	115511	167254	230038	0.0507	0.0225	-
	0.35	136916	182838	237212	0.0409	0.0409	0.0127
<hr/>							
$\tilde{B}=200$		$\tilde{A}-\tilde{A}$			<i>Deforestation rate ($\tilde{A} \rightarrow \tilde{A}$)</i>		
		$\alpha = 0$	$\alpha = 0.025$	$\alpha = 0.05$	$\alpha = 0$	$\alpha = 0.025$	$\alpha = 0.05$
$\sigma =$	0	148860	200849	249098	-	-	-
	0.05	167380	204856	249976	0.0014	-	-
	0.1	183246	213269	252285	0.0056	-	-
	0.15	196794	222214	255349	0.0127	-	-
	0.2	208333	230394	258584	0.0225	-	-
	0.25	218145	237519	261647	0.0254	0.0070	-
	0.3	226482	243606	264385	0.0507	0.0225	-
	0.35	233566	248764	266759	0.0691	0.0409	0.0127

Table 2: *Optimal forest stock and long-run average rate of deforestation under first-best with $c = 0$*

We observe that the optimal forest stock is increasing in both expected trend, α , and volatility, σ , of the level of payments for ES. The insight behind this result is standard in the real option literature. Since with higher α and/or σ development is induced by lower levels of B then conversion is postponed and the optimal converted surface corresponding to a given \tilde{B} must be lower. We note that for high level of α and σ , the forest stock should be almost intact. Long-run average rate of deforestation are null for $\alpha \geq \frac{1}{2}\sigma^2$. For this range of values, the expected trend, α , is in fact strong enough to take the level of B far from the conversion barrier. For $\alpha < \frac{1}{2}\sigma^2$ the deforestation rate is decreasing in α and increasing in σ . As discussed above this depends on the different sign of the impact that changes in these parameters have on the regulated process

ξ and the upper reflecting barrier $\hat{\xi}$.

$\bar{B}=75$		$\bar{A}-\bar{A}$			<i>Deforestation rate ($\bar{A} \rightarrow \bar{A}$)</i>		
		$\alpha = 0$	$\alpha = 0.025$	$\alpha = 0.05$	$\alpha = 0$	$\alpha = 0.025$	$\alpha = 0.05$
$\sigma =$	0	21371	100361	196683	0	-	-
	0.05	47237	107365	198722	0.0010	-	-
	0.1	71297	122587	204144	0.0042	-	-
	0.15	93425	139593	211476	0.0097	-	-
	0.2	113570	155952	219394	0.0177	-	-
	0.25	131747	170889	227067	0.0284	0.0060	-
	0.3	148028	184202	234081	0.0418	0.0196	-
	0.35	162520	195910	240283	0.0581	0.0360	0.0119
<hr/>							
$\bar{B}=200$		$\bar{A}-\bar{A}$			<i>Deforestation rate ($\bar{A} \rightarrow \bar{A}$)</i>		
		$\alpha = 0$	$\alpha = 0.025$	$\alpha = 0.05$	$\alpha = 0$	$\alpha = 0.025$	$\alpha = 0.05$
$\sigma =$	0	170889	209968	250826	-	-	-
	0.05	184295	213177	251618	0.0012	-	-
	0.1	196222	220017	253711	0.0050	-	-
	0.15	206752	227445	256510	0.0113	-	-
	0.2	215987	234385	259492	0.0204	-	-
	0.25	224046	240551	262341	0.0323	0.0066	-
	0.3	231048	245913	264911	0.0470	0.0213	-
	0.35	237117	250525	267157	0.0645	0.0389	0.0124

Table 3: Optimal forest stock and long-run average rate of deforestation under first-best with $c = 500$

By comparing the picture drawn by our tables and the available data, it is immediate to realize that the level of currently conserved land is in the most part of cases well below the optimal levels. We note that only for $\bar{B} = 75$ and with low levels of α and σ the current forest stock is in line or above the optimal levels. This implies that, on average, the past deforestation rates have been considerably higher than the optimal ones.

Thus, on the basis of these considerations, the crucial question becomes: given that 207375 hectares have been developed then how long it takes to clear the targeted surface $\bar{A} = 281375$? We answer this question by taking a different perspective. In the previous section given a certain \bar{B} we computed the optimal forest stock and the associated deforestation rate. Here, on the contrary, we establish a common initial converted land surface, $A_0 = 207375$, and calculate the long-run average deforestation rate and the relative expected time of total conversion for different levels of α , σ and c .

In table 4 we observe that the expected time required for exhausting the forest stock decreases with uncertainty. This result can be easily explained addressing the reader to the relationship between average deforestation rate and volatility previously discussed. This effect is partially balanced by higher conversion cost and higher expected growth in the payments for ES. In terms of delayed conversion, the effect of α is more remarkable. In fact, note that with low uncertainty ($\sigma \in [0, 0.1]$) it is possible to deter conversion, even

if costless ($c = 0$), by simply guaranteeing a higher expected growth in the payments (see figure 8).⁴³

$\bar{B}=75$		<i>Expected time</i>			<i>Deforestation rate ($A_0 \rightarrow \bar{A}$)</i>		
		$\alpha = 0$	$\alpha = 0.025$	$\alpha = 0.05$	$\alpha = 0$	$\alpha = 0.025$	$\alpha = 0.05$
$c=0$							
$\sigma =$	0	∞	∞	∞	0	-	-
	0.05	7962	∞	∞	0.0014	-	-
	0.1	1995	∞	∞	0.0056	-	-
	0.15	890	∞	∞	0.0127	-	-
	0.2	503	∞	∞	0.0225	-	-
	0.25	324	1597	∞	0.0352	0.0070	-
	0.3	227	503	∞	0.0507	0.0225	-
	0.35	168	280	890	0.0691	0.0409	0.0127
$c=500$							
$\sigma =$	0	∞	∞	∞	0	-	-
	0.05	8886	∞	∞	0.0013	-	-
	0.1	2226	∞	∞	0.0050	-	-
	0.15	992	∞	∞	0.0114	-	-
	0.2	561	∞	∞	0.0202	-	-
	0.25	361	1782	∞	0.0316	0.0063	-
	0.3	252	561	∞	0.0454	0.0202	-
	0.35	187	312	992	0.0619	0.0366	0.0114

Table 4: Long-run deforestation rates and timing with $c = 0$ and $c = 500$

⁴³Our findings seem in contrast with the calibration used in Leroux et al. (2009) where the authors assume a deforestation rate equal to 2.5 with $\alpha = 0.05$ and $\sigma = 0.1$. In fact, we show that for those values the deforestation rate should be null. A 2.5% deforestation rate would be justified only for lower α and higher σ .

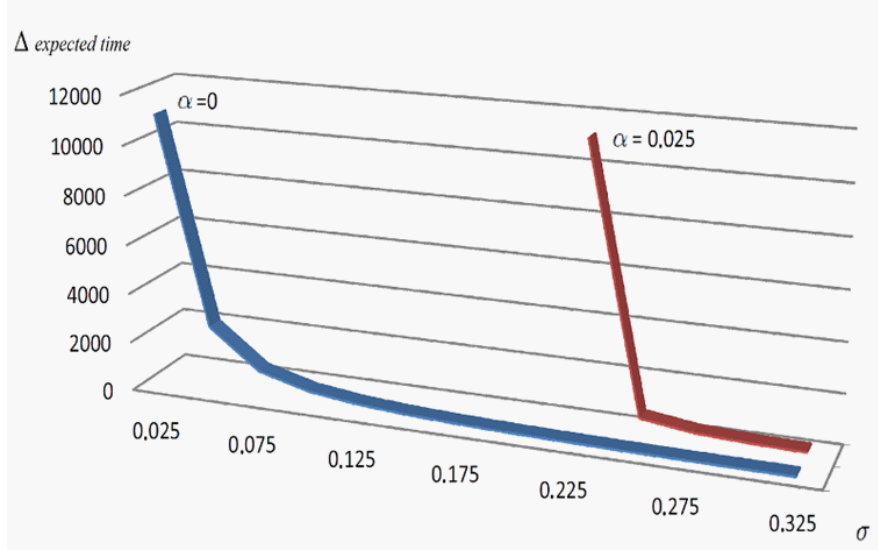


Figure 8: *Difference in expected time for total conversion between $c = 500$ and $c = 0$ with $\alpha = 0$ and $\alpha = 0.025$.*

6.2 Optimal forest stock and long-run average rate of deforestation under second-best policy

In this section, we focus on the implications of a second-best approach to conservation policies. Our analysis will consider three main scenarios (see table 5). In the first one, we will highlight the impact on conservation of a reduction in the compensation for ES provision (scenario 1) while in scenarios 2 and 3 we will study the role of compensation for a restriction on land development.⁴⁴ We will not discuss the effect of parameters \tilde{B} , α , σ and c since they are perfectly in line with the analysis under first-best. We will rather concentrate on the peculiar characteristics of second-best conservation policies.

	η_1	η_2	λ	Ψ
Scenario 1	0.7	0	0	1.4286
Scenario 2	1	0	0.3	0.7
Scenario 3	0.7	0.5	0.3	1.2727

Table 5: Policy scenarios

Table 6 illustrates the dramatic impact of conversion run occurring when the ceiling on forest conservation is binding ($\bar{A} < \hat{A}$).⁴⁵ By comparing scenarios 1 and 3 with the first-best outcome the forest stock is sensibly lower. The effect is particularly drastic for $\alpha = 0$ where the forest stock would be totally exhausted. On the contrary, under scenario 2 the second-best policy is more conservative than the first-best one. This is not surprising since in this case the policy imposes no compensation on the portion set aside when developing ($\eta_2 = 0$). Note that such a policy is substantially similar to an uncompensated taking even if, differently from a taking, its provisions are accepted on a voluntary basis by signing the initial conservation contract. Interestingly, under scenario 3 the forest stock is larger than under scenario 1. In this case, even if there is a compensation for the portion set aside the restriction on land development deters conversion. We observe

⁴⁴Numerical results under other scenarios are available upon request.

⁴⁵Tables illustrating scenarios with land conversion run for $\tilde{B} = 200$ and without land conversion run ($\bar{A} \geq \hat{A}$) are available in the appendix.

that for $\alpha > 0$ deforestation would proceed at a relatively low speed under each scenario, at least up to the level A^+ where due to the conversion run the remaining forest stock is instantaneously exhausted.

$\tilde{B}=75$		$\tilde{A}-\tilde{A}$			Deforestation rate ($\tilde{A} \rightarrow A^+$)		
		$\alpha = 0$	$\alpha = 0.025$	$\alpha = 0.05$	$\alpha = 0$	$\alpha = 0.025$	$\alpha = 0.05$
Scenario 1							
$\sigma =$	0	0	38058	161593	0	-	-
	0.05	0	46654	164341	0	-	-
	0.1	0	65533	171679	0	-	-
	0.15	0	86955	181670	0	-	-
	0.2	0	107901	192552	0	-	-
	0.25	0	127330	203189	0	0.0010	-
	0.3	0	144899	212994	0	0.0032	-
	0.35	0	160552	221732	0	0.0059	0.007329
Scenario 2							
$\sigma =$	0	86631	150093	222382	0.0000	-	-
	0.05	107838	155536	223853	0.0004	-	-
	0.1	127190	167263	227753	0.0017	-	-
	0.15	144674	180201	232999	0.0038	-	-
	0.2	160333	192484	238628	0.0070	-	-
	0.25	174254	203562	244048	0.0111	0.0037	-
	0.3	186554	213325	248972	0.0163	0.0121	-
	0.35	197372	221824	253301	0.0225	0.0222	0.0099
Scenario 3							
$\sigma =$	0	0	59603	174111	0	-	-
	0.05	0	67694	176614	0	-	-
	0.1	0	85399	183290	0	-	-
	0.15	0	105382	192357	0	-	-
	0.2	0	124811	202204	0	-	-
	0.25	0	142734	211799	0	0.0015	-
	0.3	0	158860	220617	0	0.0050	-
	0.35	0	173162	228454	0	0.0092	0.00787

Table 6: Optimal forest stock and long-run average rate of deforestation under second-best with $c = 500$

Let conclude by highlighting through figures 9 and 10 the role played by the conversion cost, c . Under each policy scenario we determine (for $B = 75$, $\alpha = 0.025$ and $\sigma \in [0, 0.35]$), the first-best surface of land developed, \tilde{A} , and the surface, A^+ , triggering a conversion run. Then we plot the difference $\tilde{A} - A^+$. By comparing figure 9 and 10, the lower is c the more remarkable is the impact of the land conversion run. In other words, under both scenarios 1 and 3, $\tilde{A} > A^+$ over the entire range of σ which means that in those scenarios a conversion run, started well before having reached \tilde{A} , would have completely exhausted the forest stock by clearing land up to the ceiling \tilde{A} . The impact of lower conversion costs should then be taken seriously into account since, as shown, for $c \rightarrow 0$ landowners would rush even for expected payments

growing at a positive rate.

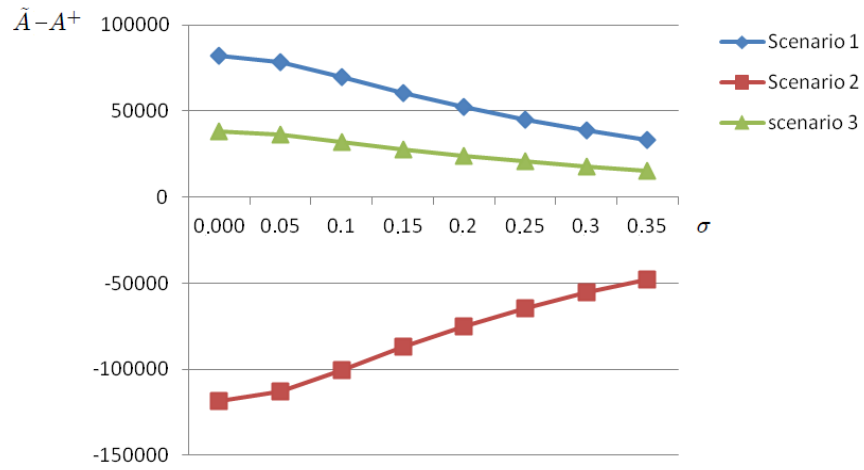


Figure 9: $\tilde{A} - A^+$ for $\tilde{B} = 75$, $\alpha = 0.025$ and $c = 0$.

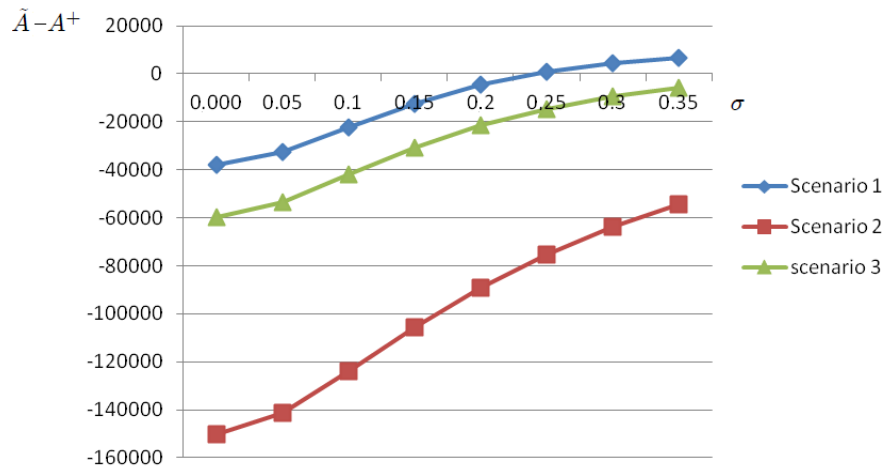


Figure 10: $\tilde{A} - A^+$ for $\tilde{B} = 75$, $\alpha = 0.025$ and $c = 500$.

7 Conclusions

In this paper we contribute to the vast literature on optimal land allocation under uncertainty and irreversible development. We extend previous work in three respects. First, departing from the standard central planner perspective we investigate the role that competing farming may have on conversion dynamics. Under competition, decreasing profits from agriculture may discourage conversion in particular if society is willing to reward habitat conservation as land use. Second, in this decentralized framework, we look at the conservation effort that Government land policy, through a combination of voluntary and command approaches, may stimulate. In this regard, an interesting result is represented by the considerable amount of conservation that the Government can induce by partially compensating agents for the ES provided. By comparing first-best and second-best conversion policies, we study the impact that different combinations of policy parameters may have on the expected conversion speed. Then, we show how the conservation payment schedule must be designed to limit the impact of set-aside requirements.

In addition, we show that the existence of a ceiling for the stock of developable land may produce perverse effects on conversion dynamics by activating a run which instantaneously exhausts the stock. Third, we believe that time matters when dynamic land allocation is analysed. Hence, we suggest the use of the optimal long-run average expected rate of conversion to assess the temporal performance of conservation policy and we show its utility by running several numerical simulations based on realistic policy scenarios.

A Appendix

A.1 Equilibrium

The value function of a farmer is given by:

$$V(A, B; \bar{A}) = Z_2(A)B^{\beta_2} + \frac{(1-\lambda)\delta}{r}A^{-\gamma} + (\lambda\eta_2 - \eta_1)\frac{B}{r-\alpha} \quad (\text{A.1.1})$$

Since each agent rationally forecasts the future dynamics of the market for agricultural goods at $B^*(A)$ she/he must be indifferent between conserving and converting. That is:

$$Z_2(A)B^*(A)^{\beta_2} + \frac{(1-\lambda)\delta}{r}A^{-\gamma} + (\lambda\eta_2 - \eta_1)\frac{B^*(A)}{r-\alpha} = (1-\lambda)c \quad (\text{A.1.2})$$

In addition, the following conditions must hold (see e.g. Proposition 1 in Bartolini (1993) and Grenadier (2002, p. 699)):

$$V_A(A, B^*(A); \bar{A}) = Z_2'(A)B^*(A)^{\beta_2} - (1-\lambda)\frac{\delta\gamma A^{-(\gamma+1)}}{r} = 0 \quad (\text{A.1.3})$$

and

$$\begin{aligned} \frac{\partial V(A, B^*(A); \bar{A})}{\partial A} &= V_A(A, B^*(A); \bar{A}) + V_B(A, B^*(A); \bar{A})\frac{dB^*(A)}{dA} \\ &= \left[\beta_2 Z_2(A) B^*(A)^{\beta_2-1} + \frac{\lambda\eta_2 - \eta_1}{r-\alpha} \right] \frac{dB^*(A)}{dA} = 0 \end{aligned} \quad (\text{A.1.4})$$

Finally, considering the limit on conversion, \bar{A} , imposed by the Government it follows that:

$$Z_2(\bar{A}) = 0 \quad (\text{A.1.5})$$

Condition (A.1.4) illustrates two scenarios. In the first one, each landholder exercises the option to convert at the level of $B^*(A)$ where the value, $V(A, B^*(A); \bar{A})$ is tangent to the conversion cost, $(1-\lambda)c$.⁴⁶ That is, $V_B(A, B^*(A); \bar{A}) = \beta_2 Z_2(A) B^*(A)^{\beta_2-1} + \frac{\lambda\eta_2 - \eta_1}{r-\alpha} = 0$. It is easy to verify that, as conjectured, $Z_2(A) < 0$. In the case $V(A, B^*(A); \bar{A})$ is smooth at the conversion threshold and $B^*(A)$ is a continuous function of A . In the second scenario, the optimal threshold $B^*(A)$ does not vary with A , i.e. $V_B(A, B^*(A); \bar{A}) \neq 0$ and $\frac{dB^*(A)}{dA} = 0$. This implies that the landholder may benefit from marginally anticipating or delaying the conversion decision. In particular, if $V_B(A, B^*(A); \bar{A}) < 0$ then the value of conversion is expected to increase as B drops. Conversely, if $V_B(A, B^*(A); \bar{A}) > 0$ then losses must be expected as B drops. However, in both cases (A.1.4) holds by imposing $\frac{dB^*(A)}{dA} = 0$.

By (A.1.4) we can split $[A_0, \bar{A}]$ into two intervals where one of the following two conditions must hold:

$$\beta_2 Z_2(A) B^*(A)^{\beta_2-1} + \frac{\lambda\eta_2 - \eta_1}{r-\alpha} = 0 \quad (\text{A.1.6})$$

$$\frac{dB^*(A)}{dA} = 0 \quad (\text{A.1.7})$$

Since $Z_2(\bar{A}) = 0$ and $\frac{\lambda\eta_2 - \eta_1}{r-\alpha} < 0$, then (A.1.6) cannot hold at $A = \bar{A}$. Therefore, (A.1.7) must hold at $A = \bar{A}$ and by (A.1.2) it follows that:

$$B^*(\bar{A}) = (r-\alpha)\Psi \left[\left(\frac{\hat{A}}{\bar{A}} \right)^\gamma - 1 \right] c \quad \text{for } A^+ \leq A \leq \bar{A} \quad (\text{A.1.8})$$

where $\hat{A} = \left(\frac{\delta}{rc} \right)^{1/\gamma}$ represents the last parcel conversion which makes economic sense. In fact, note that since $(\lambda\eta_2 - \eta_1)\frac{B}{r-\alpha} < 0$ then $\frac{\delta}{r}A^{-\gamma} \leq c$ for $A \geq \hat{A}$.

⁴⁶This condition holds at any reflecting barrier without any optimization being involved (Dixit, 1993).

Now let's define A^+ as the largest $A \leq \bar{A}$ that satisfies (A.1.6). This implies that for all the landholders in the range $A^+ \leq A \leq \bar{A}$, we have $\frac{dB^*(A)}{dA} = 0$ and conversion takes place at $B^*(\bar{A})$. Over the range $A < A^+$ (A.1.3) holds by definition. Hence, plugging (A.1.6) into (A.1.4) we obtain:

$$B^*(A) = \frac{\beta_2}{\beta_2 - 1} (r - \alpha) \Psi \left[\left(\frac{\hat{A}}{A} \right)^\gamma - 1 \right] c \quad \text{for } A < A^+ \quad (\text{A.1.9})$$

Finally, by the continuity of $B^*(A)$ follows that $B^*(A^+) = B^*(\bar{A})$.

Substituting:

$$\frac{\beta_2}{\beta_2 - 1} (r - \alpha) \Psi \left[\left(\frac{\hat{A}}{A^+} \right)^\gamma - 1 \right] c = (r - \alpha) \Psi \left[\left(\frac{\hat{A}}{\bar{A}} \right)^\gamma - 1 \right] c \quad (\text{A.1.10})$$

where

$$A^+ = \left[\frac{(\beta_2 - 1)\bar{A}^{-\gamma} + \hat{A}^{-\gamma}}{\beta_2} \right]^{-\frac{1}{\gamma}}$$

The conversion policy is summarized by (A.1.8) and (A.1.9). The conversion policy should be smooth until the surface $A^+ < \bar{A}$ has been converted. At A^+ landholders rush and a run takes place to convert the residual land before the limit imposed by the Government is met. By (A.1.9), $B^*(A)$ is decreasing with respect to A . This makes sense since further land conversion reduces the profit from agriculture and a landholder would convert land only if she/he expects a future reduction in B .

We must investigate two different scenarios, i.e. $\hat{A} \leq \bar{A}$ and $\hat{A} > \bar{A}$. From (A.1.10) it follows that:

$$\frac{\beta_2}{\beta_2 - 1} \left[\left(\frac{\hat{A}}{A^+} \right)^\gamma - 1 \right] = \left(\frac{\hat{A}}{\bar{A}} \right)^\gamma - 1 \quad (\text{A.1.10 bis})$$

Studying (A.1.10 bis) we can state that since $\frac{\beta_2}{\beta_2 - 1} > 0$:

- if $\hat{A} \leq \bar{A}$ then it must be $\bar{A} \leq A^+$. This implies that there is no run taking place. Land will be converted smoothly according to (A.1.8) up to \hat{A} since $\frac{\delta}{r} A^{-\gamma} \leq c$ for $A \geq \hat{A}$;
- if $\hat{A} > \bar{A}$ then it must be $A^+ < \bar{A}$. In this case, land is converted smoothly up to A^+ where landholders start a run to convert land up to \bar{A} .

A.2 Value of the option to convert

In this appendix we show that, by competition, the value of the opportunity to develop the plot by the single farmer is null at the conversion threshold. The value of the option to convert, $F(A, B; \bar{A})$, is the solution of the following differential equation (Dixit and Pindyck, 1994, ch. 8):

$$\frac{1}{2} \sigma^2 B^2 F_{BB}(A, B; \bar{A}) + \alpha B F_B(A, B; \bar{A}) - r F(A, B; \bar{A}) = 0 \quad \text{for } B > B^C(A) \quad (\text{A.2.1})$$

where $B^C(A)$ is the optimal threshold for conversion. Note that this is an ordinary differential equation, the general solution of which can be written as:

$$F(A, B; \bar{A}) = C_1(A) B^{\beta_1} + C_2(A) B^{\beta_2} \quad (\text{A.2.2})$$

where $1 < \beta_1 < r/\alpha$, $\beta_2 < 0$ are the positive and the negative root of the characteristic equation $\Psi(\beta) = \frac{1}{2} \sigma^2 \beta(\beta - 1) + \alpha\beta - r = 0$, and C_1, C_2 are two constants to be determined.

Since $\eta_1 \geq \eta_2$ then as B increases, the value of the option to convert should vanish ($\lim_{B \rightarrow \infty} F(A, B; \bar{A}) = 0$). This implies that $C_1 = 0$. Now, let's determine the optimal conversion threshold $B^C(A)$ and the constant $C_2(A)$. We attach to the differential equation above the following value matching and the smooth pasting conditions:

$$\begin{aligned} F(A, B^C(A); \bar{A}) &= V(A, B^C(A); \bar{A}) - (1 - \lambda) c \\ C_2(A) B^C(A)^{\beta_2} &= Z_2(A) B^C(A)^{\beta_2} + \frac{(1 - \lambda) \delta A^{-\gamma}}{r} + \frac{(\lambda \eta_2 - \eta_1) B^C(A)}{r - \alpha} - (1 - \lambda) c \end{aligned} \quad (\text{A.2.3})$$

$$\begin{aligned}
F_B(A, B^C(A); \bar{A}) &= V_B(A, B^C(A); \bar{A}) \\
\beta_2 C_2(A) B^C(A)^{\beta_2-1} &= \beta_2 Z_2(A) B^C(A)^{\beta_2-1} + \frac{\lambda \eta_2 - \eta_1}{r - \alpha}
\end{aligned} \tag{A.2.4}$$

It follows that:

$$B^C(A) = B^*(A) = \frac{\beta_2}{\beta_2 - 1} (r - \alpha) \Psi \left[\frac{\delta}{r} A^{-\gamma} - c \right]$$

From (A.1.4) we obtain $V_B(A, B^*(A); \bar{A}) = \beta_2 Z_2(A) B^*(A)^{\beta_2-1} + \frac{\lambda \eta_2 - \eta_1}{r - \alpha} = 0$ which in turn implies $Z_2(A) = -\frac{\lambda \eta_2 - \eta_1}{r - \alpha} \frac{B^*(A)^{1-\beta_2}}{\beta_2}$.

Rearranging (A.2.4) and substituting we have:

$$\begin{aligned}
C(A) &= Z_2(A) + \frac{\lambda \eta_2 - \eta_1}{r - \alpha} \frac{B^C(A)^{1-\beta_2}}{\beta_2} \\
&= \frac{\lambda \eta_2 - \eta_1}{(r - \alpha) \beta_2} (B^C(A)^{1-\beta_2} - B^*(A)^{1-\beta_2}) = 0
\end{aligned}$$

As expected the value of the option to convert is null at $B^C(A) = B^*(A)$.

A.3 Long-run distributions

Let h be a linear Brownian motion with parameters μ and σ that evolves according to $dh = \mu dt + \sigma dw$. Following Harrison (1985, pp. 90-91; see also Dixit 1993, pp. 58-68) the long-run density function for h fluctuating between a lower reflecting barrier, $a \in (-\infty, \infty)$, and an upper reflecting barrier, $b \in (-\infty, \infty)$, is represented by the following truncated exponential distribution:

$$f(h) = \begin{cases} \frac{2\mu}{\sigma^2} \frac{e^{\frac{2\mu}{\sigma^2} h}}{e^{\frac{2\mu}{\sigma^2} b} - e^{\frac{2\mu}{\sigma^2} a}} & \mu \neq 0, \\ \frac{1}{b-a} & \mu = 0. \end{cases} \tag{A.3.1}$$

We are interested to the limit case where $a \rightarrow -\infty$. In this case, from (A.3.1) a limiting argument gives:

$$f(h) = \begin{cases} \frac{2\mu}{\sigma^2} e^{-\frac{2\mu}{\sigma^2}(b-h)} & \mu > 0, \\ 0 & \mu \leq 0. \end{cases} \quad \text{for } -\infty < h < b \tag{A.3.2}$$

Hence, the long-run average of h can be evaluated as $E[h] = \int_{\Phi} h f(h) dh$, where Φ depends on the distribution assumed. In the steady-state this yields:

$$E[h] = \int_{-\infty}^b h f(h) dh = \int_{-\infty}^b h \frac{2\mu}{\sigma^2} e^{-\frac{2\mu}{\sigma^2}(b-h)} dh = \frac{2\mu}{\sigma^2} e^{-\frac{2\mu}{\sigma^2} b} \int_{-\infty}^b h e^{\frac{2\mu}{\sigma^2} h} dh = b - \frac{2\mu}{\sigma^2} \tag{A.3.3}$$

A.4 Long-run average growth rate of deforestation

Taking the logarithm of (14) we get:

$$\begin{aligned}
\ln \xi &= \ln \left[\frac{\beta_2}{\beta_2 - 1} (1 - \lambda) \frac{P_A(A)}{r} - \frac{\eta_1 - \lambda \eta_2}{r - \alpha} B \right] \\
&= \ln \left[\frac{\eta_1 - \lambda \eta_2}{r - \alpha} \right] + \ln [J - B]
\end{aligned} \tag{A.4.1}$$

where $J = \frac{\beta_2}{\beta_2 - 1} (r - \alpha) \Psi \frac{P_A(A)}{r}$ and $J > B$. Rewriting $\ln [J - B]$ as $\ln [e^{\ln J} - e^{\ln B}]$ and expanding it by Taylor's theorem around the point $(\widetilde{\ln J}, \widetilde{\ln B})$ yields:

$$\ln [J - B] \simeq v_0 + v_1 \ln J + v_2 \ln B$$

where

$$\begin{aligned} v_0 &= \ln \left[e^{\widetilde{\ln J}} - e^{\widetilde{\ln B}} \right] - \left[\frac{\widetilde{\ln J}}{1 - e^{\widetilde{\ln B} - \widetilde{\ln J}}} + \frac{\widetilde{\ln B}}{1 - e^{-(\widetilde{\ln B} - \widetilde{\ln J})}} \right] \\ v_1 &= \frac{1}{1 - e^{\widetilde{\ln B} - \widetilde{\ln J}}}, \quad v_2 = \frac{1}{1 - e^{-(\widetilde{\ln B} - \widetilde{\ln J})}}, \quad \frac{v_2}{v_1} = \frac{1 - v_1}{v_1} < 0 \end{aligned}$$

By substituting the approximation into (A.4.1) it follows that:

$$\ln \xi \simeq \ln \frac{\eta_1 - \lambda \eta_2}{r - \alpha} + v_0 + v_1 \ln J + v_2 \ln B \quad (\text{A.4.2})$$

Now, by Ito's lemma and the considerations discussed in the paper on the competitive equilibrium, $\ln \xi$ evolves according to $d \ln \xi = v_2 d \ln B = v_2 [(\alpha - \frac{1}{2} \sigma^2) dt + \sigma dw]$ with $\ln \hat{\xi}$ as upper reflecting barrier. Setting $h = \ln \xi$, the random variable $\ln \xi$ follows a linear Brownian motion with parameter $\mu = v_2(\alpha - \frac{1}{2} \sigma^2) > 0$ and has a long-run distribution with (A.3.2) as density function.

Solving (A.4.2) with respect to $\ln A$ we obtain the long-run optimal stock of deforested land, i.e.:

$$\ln A \simeq \frac{\ln \left[\frac{\eta_1 - \lambda \eta_2}{r - \alpha} \right] + v_0 + v_1 \ln \left[\frac{\beta_2}{\beta_2 - 1} (r - \alpha) \Psi \frac{\delta}{r} \right] + v_2 \ln B - h}{\gamma v_1} \quad (\text{A.4.3})$$

From (A.4.3) by some manipulations we can show that

$$\begin{aligned} 1 &= \exp\left(\frac{v_0}{v_1}\right) \left(\frac{\eta_1 - \lambda \eta_2}{r - \alpha} \frac{1}{\hat{\xi}}\right)^{\frac{1}{v_1}} \left[\frac{\beta_2}{\beta_2 - 1} (r - \alpha) \Psi \frac{\delta}{r} \right] A^{-\gamma} B^{\frac{v_2}{v_1}} \\ &= \exp\left(\frac{v_0}{v_1}\right) \left[\frac{\beta_2}{\beta_2 - 1} (r - \alpha) \Psi \right]^{\frac{v_2}{v_1}} \frac{\delta}{r} c^{-\frac{1}{v_1}} A^{-\gamma} B^{\frac{v_2}{v_1}} \\ &= \exp\left(\frac{v_0}{v_1}\right) \left(\frac{J}{\frac{\delta}{r} A^{-\gamma}}\right)^{-\frac{v_2}{v_1}} \frac{\delta}{r} c^{-\frac{1}{v_1}} A^{-\gamma} B^{\frac{v_2}{v_1}} \\ &= \exp\left(\frac{v_0}{v_1}\right) J^{-\frac{v_2}{v_1}} \left(\frac{\delta}{rc} A^{-\gamma}\right)^{\frac{1}{v_1}} B^{\frac{v_2}{v_1}} \\ &= \exp(v_0) J^{-v_2} \left(\frac{\hat{A}}{A}\right)^{\gamma} B^{v_2} \\ &= \frac{\tilde{J} - \tilde{B}}{\tilde{J}^{v_1} \tilde{B}^{v_2}} J^{-v_2} \left(\frac{\hat{A}}{A}\right)^{\gamma} B^{v_2} \\ &= \left(\frac{\hat{A}}{A}\right) \left(\frac{B}{\tilde{B}}\right)^{-\frac{1}{\gamma} [1 - (\frac{\hat{A}}{A})^{\gamma}]} \end{aligned}$$

and

$$\frac{A}{\hat{A}} = \left(\frac{B}{\tilde{B}}\right)^{-\frac{1}{\gamma} [1 - (\frac{\hat{A}}{A})^{\gamma}]}$$

Note that since $\tilde{A} < \hat{A}$ then $-\frac{1}{\gamma} [1 - (\frac{\hat{A}}{A})^{\gamma}] < 0$.

Taking the expected value on both sides of (A.4.3) leads to:

$$E[\ln A] \simeq \frac{\ln \left[\frac{\eta_1 - \lambda \eta_2}{r - \alpha} \right] + v_0 + v_1 \ln \left[\frac{\beta_2}{\beta_2 - 1} (r - \alpha) \Psi \frac{\delta}{r} \right] + v_2 [B_0 + (\alpha - \frac{1}{2} \sigma^2) t] - E[h]}{\gamma v_1}$$

Since by (A.3.3) $E(h)$ is independent on t , differentiating with respect to t , we obtain the expected long-run rate of deforestation:

$$\begin{aligned} \frac{1}{dt} E[d \ln A] &\simeq \frac{v_2 \alpha - \frac{1}{2} \sigma^2}{v_1 \gamma} \\ &= -\frac{\alpha - \frac{1}{2} \sigma^2}{\gamma} e^{\widetilde{\ln B} - \widetilde{\ln J}} \quad \text{for } \alpha < \frac{1}{2} \sigma^2 \end{aligned}$$

By the monotonicity property of the logarithm, \widetilde{B} must exist such that $\ln \widetilde{B} = \widehat{\ln B}$. Furthermore, by plugging \widetilde{B} into (10), we can always find a surface \widetilde{A} and $\widetilde{J} = \frac{\beta_2}{\beta_2 - 1} (r - \alpha) \Psi \frac{P_A(\widetilde{A})}{r}$ such that a linearization along $(\widehat{\ln B}, \widehat{\ln J})$ is equivalent to a linearization along $(\ln \widetilde{B}, \ln \widetilde{J})$, where $\widehat{\ln J} = \ln \widetilde{J}$. This implies that by setting $(\widetilde{B}, \widetilde{A})$, the long-run average rate of deforestation can be written as:

$$\begin{aligned} \frac{1}{dt} E[d \ln A] &= -\frac{\alpha - \frac{1}{2}\sigma^2}{\gamma} \frac{\widetilde{B}}{\widetilde{J}} = -\frac{\alpha - \frac{1}{2}\sigma^2}{\gamma} \frac{1}{1 + \frac{\beta_2}{\beta_2 - 1} (r - \alpha) \Psi \frac{c}{\widetilde{B}}} \\ &= -\frac{\alpha - \frac{1}{2}\sigma^2}{\gamma} \frac{\frac{P_A(\widetilde{A})}{r} - c}{\frac{P_A(\widetilde{A})}{r}} = -\frac{\alpha - \frac{1}{2}\sigma^2}{\gamma} \left(1 - \frac{c}{\frac{\delta}{r} \widetilde{A}^{-\gamma}}\right) \end{aligned}$$

where $\frac{P_A(\widetilde{A})}{r} = \frac{\widetilde{B}}{\frac{\beta_2}{\beta_2 - 1} (r - \alpha) \Psi} + c$ and $\widetilde{A} < \widehat{A}$.

A.5 The impact of uncertainty on the distribution of ξ

Rearranging (A.4.2) yields

$$\ln \xi \simeq U_\xi + v_2 \ln B \quad (\text{A.5.1})$$

where $U_\xi = \ln \frac{\eta_1 - \lambda \eta_2}{r - \alpha} + v_0 + v_1 \ln J$.

By some manipulations:

$$\begin{aligned} e^{\ln \xi} &= e^{U_\xi + v_2 \ln B} \\ \xi &= e^{U_\xi} B^{v_2} \end{aligned} \quad (\text{A.5.2})$$

Using Ito's lemma

$$\begin{aligned} d\xi &= e^{U_\xi} \left[v_2 B^{v_2 - 1} dB + \frac{1}{2} v_2 (v_2 - 1) B^{v_2 - 2} (dB)^2 \right] \\ &= e^{U_\xi} B^{v_2} v_2 \left\{ \left[\alpha + \frac{1}{2} (v_2 - 1) \sigma^2 \right] dt + \sigma dw \right\} \\ &= \xi v_2 \left\{ \left[\alpha + \frac{1}{2} (v_2 - 1) \sigma^2 \right] dt + \sigma dw \right\} \end{aligned}$$

Calculating first, second moment and variance for ξ we obtain:

$$\begin{aligned} E(\xi) &= \xi(0) e^{v_2 [\alpha + \frac{1}{2} (v_2 - 1) \sigma^2] t} \\ E(\xi^2) &= \xi^2(0) e^{2v_2 [\alpha + (v_2 - \frac{1}{2}) \sigma^2] t} \\ Var(\xi) &= \xi^2(0) e^{2v_2 [\alpha + \frac{1}{2} (v_2 - 1) \sigma^2] t} (e^{v_2^2 \sigma^2 t} - 1) \end{aligned}$$

Note that since $\alpha + \frac{1}{2} (v_2 - 1) \sigma^2 < 0$ and $v_2 < 0$ then $E(\xi)$ is increasing in t . Finally, by deriving $Var(\xi)$ with respect to σ it is easy to check that

$$\frac{\partial Var(\xi)}{\partial \sigma} = 2v_2 \sigma t e^{2v_2 [\alpha + \frac{1}{2} (v_2 - 1) \sigma^2] t} \xi^2(0) \left[(v_2 - 1) (e^{v_2^2 \sigma^2 t} - 1) + v_2 e^{v_2^2 \sigma^2 t} \right] > 0$$

That is, as σ soars $Var(\xi)$ increases and so does the probability of hitting $\widehat{\xi}$ which in turn implies an increase in the long run average deforestation rate.

A.6 Additional tables

With land conversion run

$\tilde{B}=200$		$\bar{A}-\tilde{A}$			<i>Deforestation rate ($\tilde{A} \rightarrow A^+$)</i>		
		$\alpha = 0$	$\alpha = 0.025$	$\alpha = 0.05$	$\alpha = 0$	$\alpha = 0.025$	$\alpha = 0.05$
<i>Scenario 1</i>							
$\sigma =$	0	127331	179609	236733	-	-	-
	0.05	145022	184000	237868	0.0006	-	-
	0.1	160972	193411	240873	0.0024	-	-
	0.15	175223	203715	244902	0.0056	-	-
	0.2	187858	213421	249211	0.0102	-	-
	0.25	198989	222111	253344	0.0161	0.0044	-
	0.3	208745	229718	257085	0.0236	0.0144	-
	0.35	217263	236302	260364	0.0324	0.0263	0.0106
<i>Scenario 2</i>							
$\sigma =$	0	203562	231923	260606	-	-	-
	0.05	213393	234212	261153	0.0010	-	-
	0.1	222049	239070	262594	0.0039	-	-
	0.15	229622	244315	264517	0.0089	-	-
	0.2	236211	249185	266560	0.0161	-	-
	0.25	241918	253488	268507	0.0253	0.0057	-
	0.3	246847	257210	270259	0.0367	0.0184	-
	0.35	251094	260398	271786	0.0502	0.0335	0.0116
<i>Scenario 3</i>							
$\sigma =$	0	142735	190489	241860	-	-	-
	0.05	158973	194469	242872	0.0007	-	-
	0.1	173545	202980	245549	0.0027	-	-
	0.15	186509	212273	249135	0.0063	-	-
	0.2	197960	221001	252965	0.0114	-	-
	0.25	208014	228793	256633	0.0180	0.0047	-
	0.3	216799	235599	259949	0.0262	0.0152	-
	0.35	224448	241476	262852	0.0361	0.0278	0.0108

Table 7: Optimal forest stock and long-run average rate of deforestation under second-best with $\tilde{B} = 200$ and $c = 500$

No Rush

$\tilde{B}=75$		$\tilde{A}-\tilde{A}$			Deforestation rate ($\tilde{A} \rightarrow \tilde{A}$)		
		$\alpha = 0$	$\alpha = 0.025$	$\alpha = 0.05$	$\alpha = 0$	$\alpha = 0.025$	$\alpha = 0.05$
<i>Scenario 1</i>							
$\sigma =$	0	107901	138140	193785	0	-	-
	0.05	116765	141343	195315	0.0005	-	-
	0.1	125859	148671	199482	0.0022	-	-
	0.15	135067	157518	205353	0.0054	-	-
	0.2	144268	166774	212023	0.0103	-	-
	0.25	153344	175960	218844	0.0173	0.0040	-
	0.3	162192	184821	225417	0.0265	0.0136	-
	0.35	170721	193209	231523	0.0382	0.0259	0.0099
<i>Scenario 2</i>							
$\sigma =$	0	157379	187550	231987	0	-	-
	0.05	166745	190468	233043	0.0008	-	-
	0.1	175891	196960	235877	0.0032	-	-
	0.15	184704	204475	239773	0.0076	-	-
	0.2	193088	211981	244067	0.0143	-	-
	0.25	200973	219089	248318	0.0234	0.0052	-
	0.3	208310	225644	252283	0.0350	0.0171	-
	0.35	215076	231588	255857	0.0494	0.0319	0.0111
<i>Scenario 3</i>							
$\sigma =$	0	115552	146324	200889	0	-	-
	0.05	124654	149537	202353	0.0006	-	-
	0.1	133922	156855	206327	0.0024	-	-
	0.15	143233	165627	211901	0.0058	-	-
	0.2	152463	174734	218199	0.0110	-	-
	0.25	161497	183699	224600	0.0183	0.0042	-
	0.3	170235	192278	230730	0.0279	0.0142	-
	0.35	178595	200339	236392	0.0401	0.0270	0.0101

Table 8: Optimal forest stock and long-run average rate of deforestation under second-best with $\tilde{B} = 75$ and $c = 1500$

Without land conversion run

$\tilde{B}=200$		$\bar{A}-\tilde{A}$			<i>Deforestation rate ($\tilde{A} \rightarrow \bar{A}$)</i>		
		$\alpha = 0$	$\alpha = 0.025$	$\alpha = 0.05$	$\alpha = 0$	$\alpha = 0.025$	$\alpha = 0.05$
<i>Scenario 1</i>							
$\sigma =$	0	175960	204123	242608	0	-	-
	0.05	184885	206756	243480	0.0009	-	-
	0.1	193441	212563	245813	0.0036	-	-
	0.15	201538	219190	248999	0.0084	-	-
	0.2	209110	225710	252479	0.0156	-	-
	0.25	216114	231793	255893	0.0254	0.0055	-
	0.3	222534	237325	259051	0.0378	0.0181	-
	0.35	228369	242278	261873	0.0530	0.0336	0.0115
<i>Scenario 2</i>							
$\sigma =$	0	219090	238966	262084	0	-	-
	0.05	225690	240688	262560	0.0011	-	-
	0.1	231749	244409	263823	0.0044	-	-
	0.15	237254	248530	265525	0.0102	-	-
	0.2	242209	252457	267355	0.0185	-	-
	0.25	246633	256013	269120	0.0296	0.0062	-
	0.3	250559	259157	270726	0.0434	0.0201	-
	0.35	254025	261903	272141	0.0601	0.0370	0.0121
<i>Scenario 3</i>							
$\sigma =$	0	183699	210736	246588	0	-	-
	0.05	192340	213230	247386	0.0009	-	-
	0.1	200561	218708	249516	0.0037	-	-
	0.15	208283	224924	252417	0.0088	-	-
	0.2	215453	231002	255576	0.0162	-	-
	0.25	222043	236642	258665	0.0262	0.0056	-
	0.3	228046	241741	261513	0.0389	0.0185	-
	0.35	233472	246286	264050	0.0544	0.0343	0.0116

Table 9: Optimal forest stock and long-run average rate of deforestation under second-best with $\tilde{B} = 200$ and $c = 1500$

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