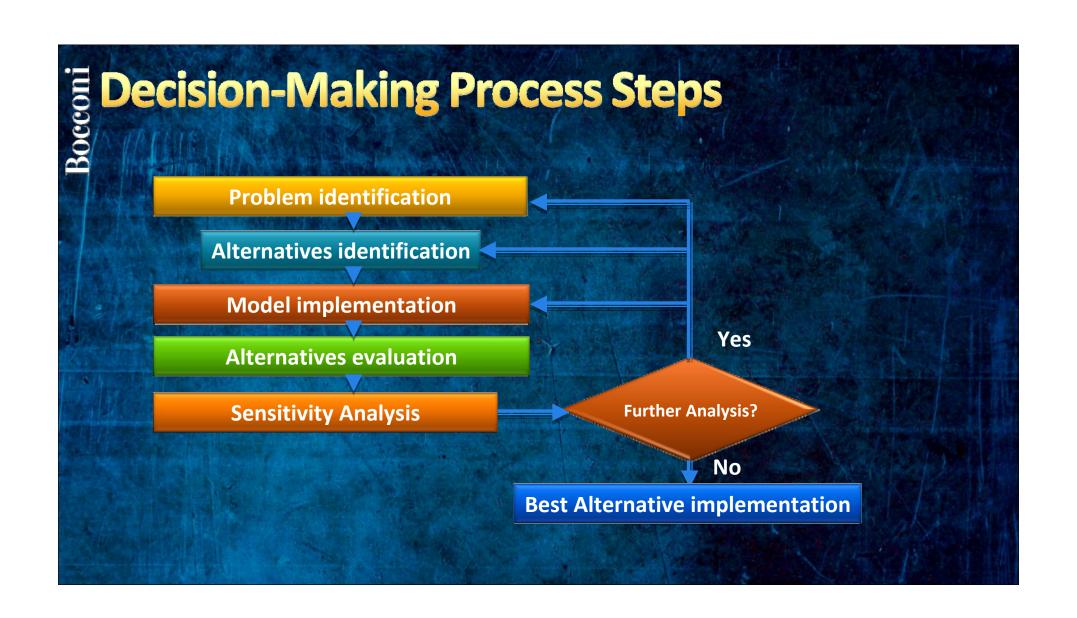
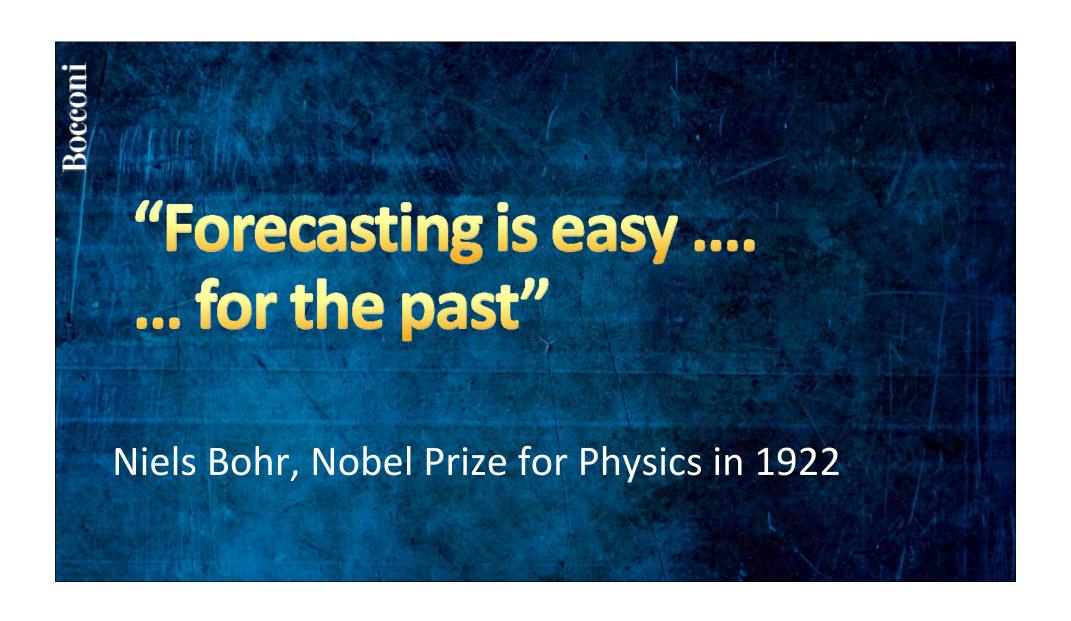
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Uncertainty in Integrated Assessment Modelling: Can Global Sensitivity be of Help?

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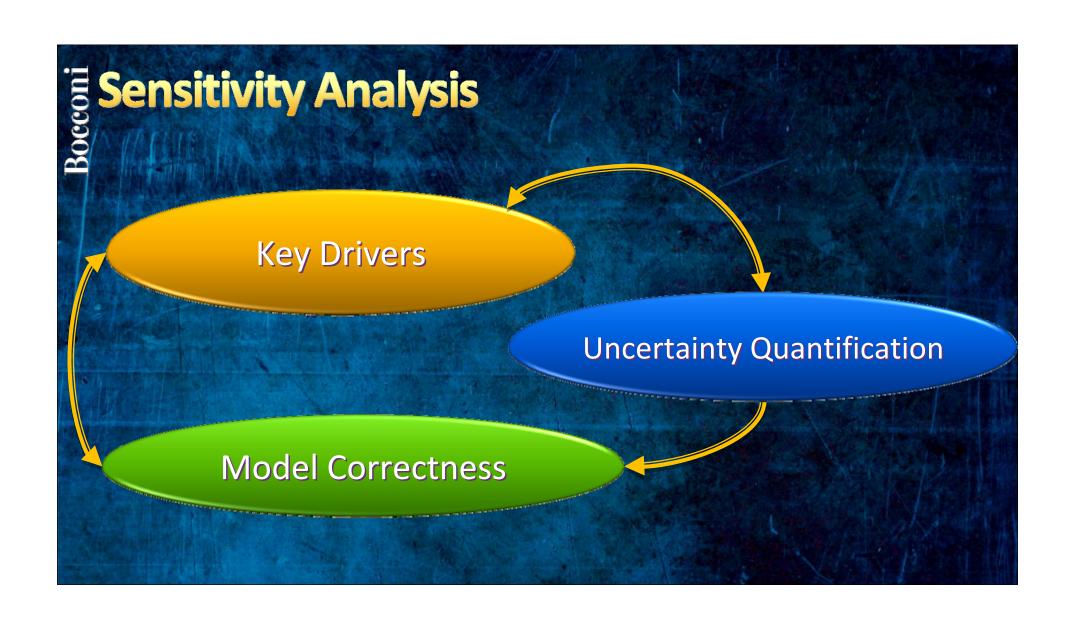


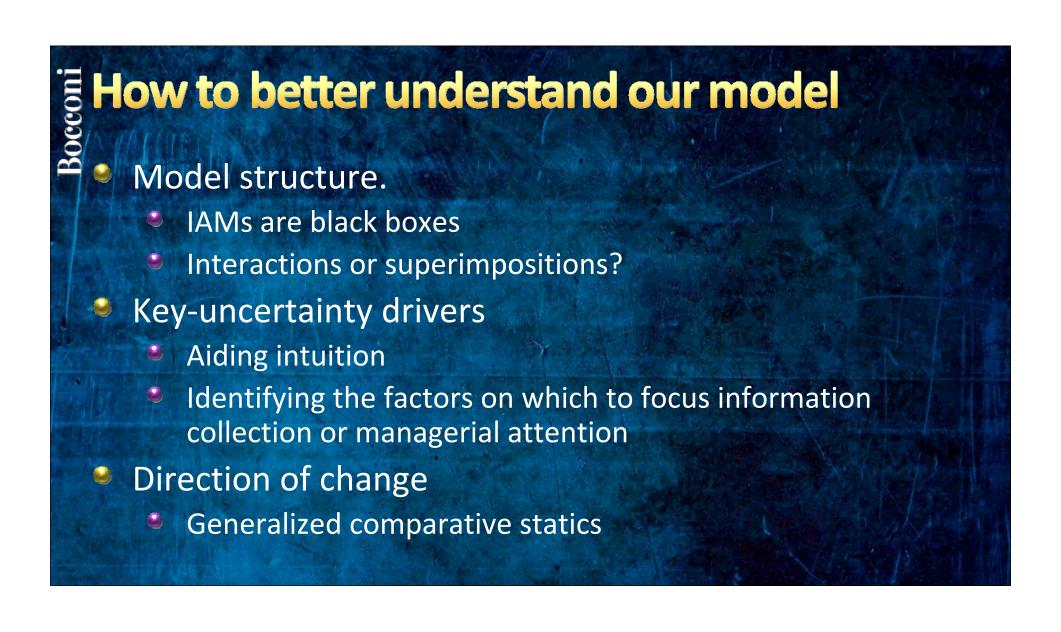
The Problem I

- Uncertainties pervade forecasts in environmental and climate change sciences
- Environmental models are nowadays intermediaries between science and policy [Risbey et al (2005, EMA)].
- If uncertainties are not properly
 - Assessed
 - Communicated
- one runs the risk of model rejection by stakeholders (Saltelli and d'Hombres (2010), GEC); Stokstadt (2008; Science)).

The Problem II

- "Dealing consistently with risk and uncertainty across the Intergovernmental Panel on Climate Change (IPCC) reports is a difficult challenge" (Swart et al, 2009; p.3; CC) and that "observed differences in handling uncertainties by the three IPCC working groups emerge" [ibidem](p.1).
- See also the work of Webster (2009, CC), Oppenheimer et al. (2007; Science).
- There is uncertainty in practically every factor that enters in an IAM.



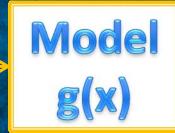


Setting

- Ω_X set of possible values that the model inputs can assume
- \bullet $(\Omega_X, B(\Omega_X), \mathbf{P})$ corresponding probability space
- Input output mapping

$$y = g(\mathbf{x}) : \Omega_{\mathbf{x}} \subseteq \mathbf{R}^n \to \mathbf{R}$$

Input (x)



Output (y)

Model Structure I

Efron and Stein (1981), Sobol' (1993) Rabitz and Alis (1999). g(x) integrable

$$g(\mathbf{x}) = g_0 + \sum_{i=1}^n g_i(x_i) + \sum_{i< j}^n g_{ij}(x_i, x_j) + \dots + g_{1,2,\dots,n}(x_1, x_2, \dots, x_n)$$

$$g_0 = \mathbb{E}_{\mathbf{X}}[g(\mathbf{X})] = \int ... \int g(\mathbf{X}) \prod_{i=1}^n dF_i$$

$$g_i(x_i) = \mathbb{E}_{\mathbf{X}}[g(\mathbf{X}) | X_i = x_i] - g_0 = \int ... \int g(\mathbf{X}) \prod_{s=1, s \neq i}^n dF_s$$

$$g_{i}(x_{i}) = \mathbb{E}_{\mathbf{X}}[g(\mathbf{X}) \mid X_{i} = x_{i}, X_{j} = x_{j}] - g_{i}(x_{i}) - g_{j}(x_{j}) - g_{0} = \int ... \int g(\mathbf{X}) \prod_{s=1, s \neq i, j}^{n} dF_{s}$$

•••••

Model Structure II

By orthogonality

$$V_{X}[Y] = \sum_{i=1}^{n} V_{i} + \sum_{i=1}^{n} V_{ij} + ... + V_{1,2,...,n}$$

Sobol' Global sensitivity indices:

$$S_l^1 \equiv \frac{V_l}{V_X[Y]} = \frac{V_{X_l}[\mathbb{E}\{Y | X_l\}]}{V_X[Y]}$$

If sum of S_I is close to unity, then the model is additive

Monotonicity

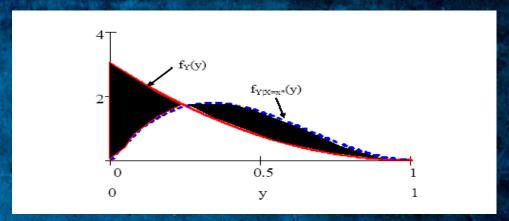
By knowledge of the functions

$$E[Y | X_i = x_i] = g_i(x_i) - g_0$$

- Average behavior over the entire variation range of X_i
- Difference with respect to partial derivatives
- Exact behavior if g(x) is additive

The intuition

Conditioning on X_i=x_i*



If Y is independent of xi then its distribution will not change. However, if its distribution changes significantly, then the decision maker view of Y changes significantly.

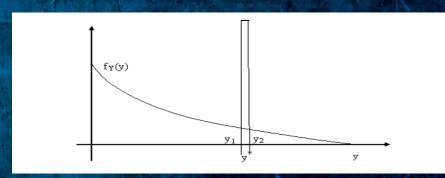
The δ importance measure

We then define the importance of an Individual parameter (Borgonovo, 2006, 2007)

$$\delta_{i} = \frac{1}{2} \mathbb{E} \left[\int \left| f_{Y}(y) - f_{Y|X_{l} = x_{l}}(y) \right| dy \right]$$

Properties

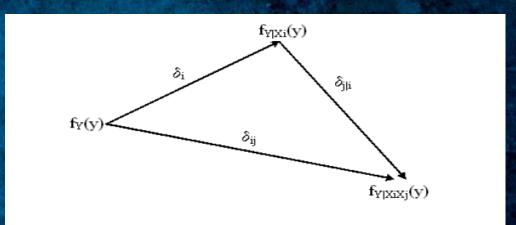
- 1. $0 \le \delta_{l} \le 1$
 - ☐ Proof: based on the triangle inequality
- 2. δ_{l} =0 if Y is independent of X_l
 - \square Proof: $f_{Y}(y) = f_{Y|X|(y)}$
- 3. $\delta_{1,2,...,n} = 1$ Proof: limit, Dirac- δ



Properties (continued)

4. $\delta_{ij} = \delta_i$ if Y depedendent on X_i , indep. of X_j

5. $\delta_{i} \leq \delta_{ij} \leq \delta_{i} + \delta_{j|i|}$



6. Invariant for Monotonic Transformation of Y

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Properties

- Normalization: $0 \le \delta_i \le 1$
- Joint normalization: $0 \le \delta_{1,2,...,n} \le 1$
- Scale Invariance

For any X and Y on measurable spaces $(\mathfrak{X}, \mathcal{A})$ and $(\mathfrak{Y}, \mathfrak{B})$, it holds that

$$\delta(Y,X) = \delta(X,Y) = \frac{1}{2} \int_{\mathcal{X} \times \mathcal{Y}} |f_X(x)f_Y(y) - f_{XY}(x,y)| \, \mathrm{d}y \, \mathrm{d}x.$$

Plischke, Borgonovo and Smith (2012)

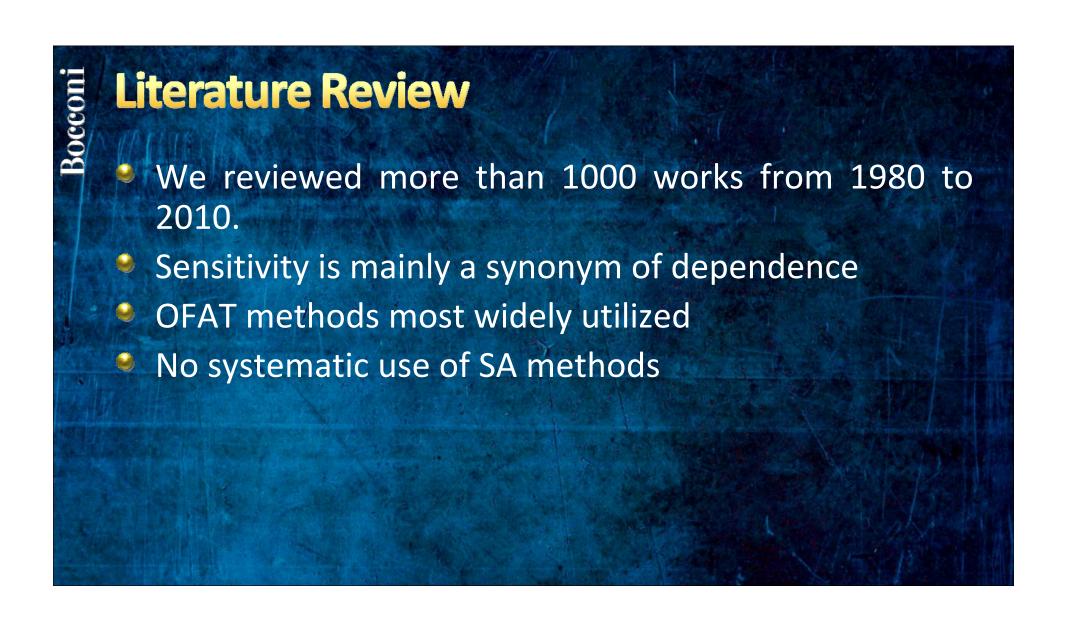
Estimation

- Several ways for estimating these sensitivity measures in the literature
- We utilize a method that allows one to perform a simple Monte Carlo Simulation and extract the sensitivity measures directly from such dataset (post-processing)
- For variance-based sensitivity measures Ziehn and Tomlin (2009)
- For density-based Plischke et al (2012)
- Notable computational burden reduction



State of the art

- Monte Carlo simulation part of best practices in the IAM literature.
- Uncertainty analysis of the DICE model (Nordhaus, 1994, 2008) and PAGE model (Hope, 2006).
- Dietz (2011) assessment of catastrophic climate change based on the PAGE model
- Popp (2004) using ENTICE, an adaptation of the DICE model.
- Three studies:
 - van Vuuren et al. (2008) apply a probabilistic approach to an energy model,
 - Hof et al. (2008) use the FAIR IAM
 - Anthoff and Tol (2011) effects of uncertainty on the social cost of carbon (current damages caused by each unit of emissions) using the FUND model.
- Raw correlations or standardized regression coefficients. The SA literature describes specifically the weaknesses of using correlations or standardized regression coefficients



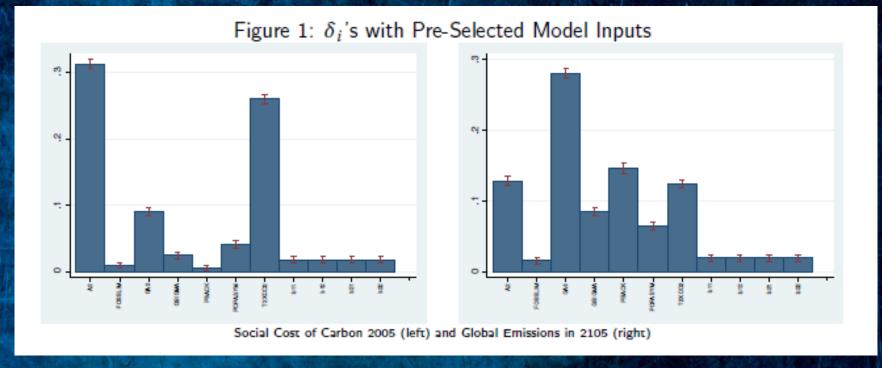
The DICE Model

- We refer to Nordhaus (1994) and Nordhaus (2008) for details
- 51 factors (model inputs)
- The model consists of a set of interconnected equations and outputs the following quantities of interest:
 - Inter-generational welfare (utility),
 - social cost of carbon in 2005,
 - global atmospheric temperature in 2105,
 - global emission level in 2105,
 - optimal carbon tax for 2015

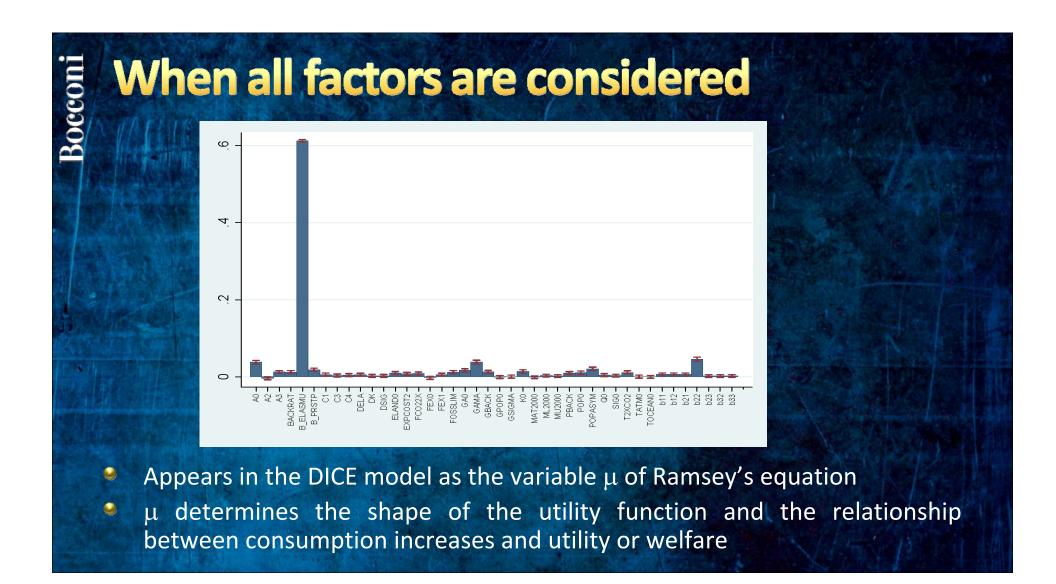
Nordhaus's Results

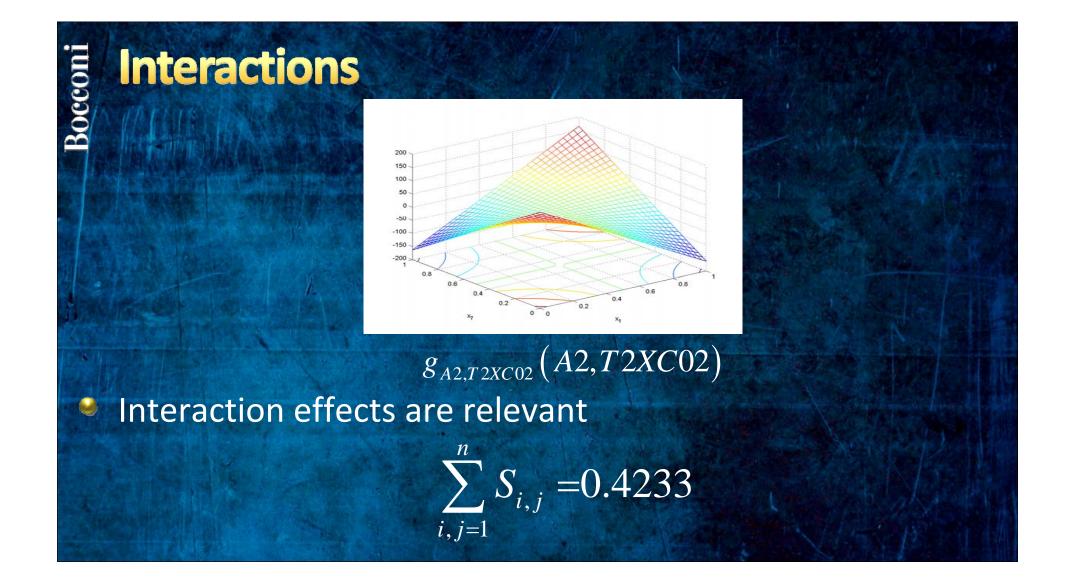
- Performs a seires of OFAT Analysis to lower the number of inputs
- Then assesses uncertainty on 8 factors.
- Weaknesses:
 - Ranking is dependent on the variation range
 - No systematic identification
- We use 10000 model runs on these 8 factors and display the Bootstrap-Bias-corrected estimator used in Plischke et al (2012)

On Nordhaus' 8 factors



the coefficient in the damage function (A2), climate sensitivity (T2XCO2) and the growth rate of total factor productivity (GA0) are the most influential inputs

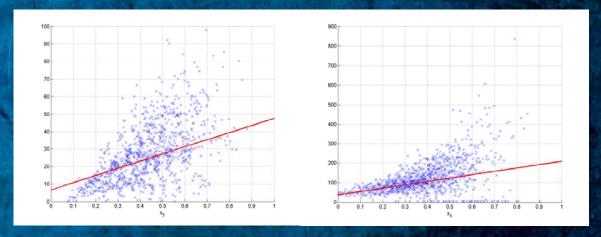




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Monotonicity

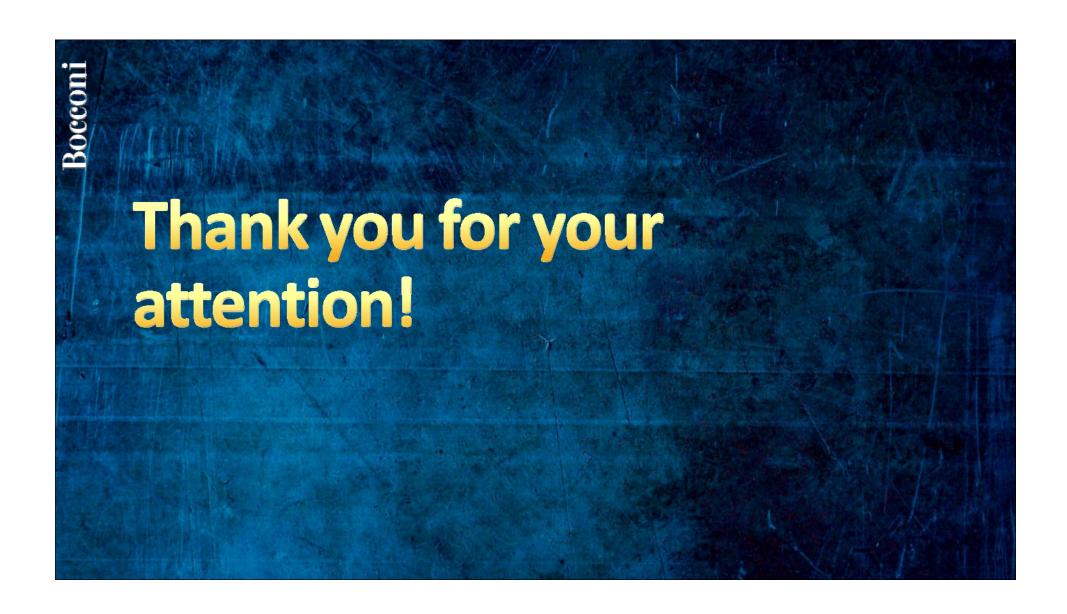
Plotting the first order functions one gains insights of what happens to the model when factors vary individually



SCC vs T2XCO2 and Global emission vs GA0 (right)

Conclusions

- Systematic approach for inferring insights from models
- Several sensitivity questions can be asked
 - Model structure
 - Monotonicity
 - Key-Uncertainty Drivers
- Approach rigorous, avoids pitfalls
- Computationally Convenient, because in a postprocessing mode



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